

Lecture 2-13-1 - Polynomial systems,
computer algebra and applications

Jean-Charles Faugère

Change the ordering (FGLM)

Algebraic Cryptanalysis

Linear Algebra

Characterizations of Gröbner Bases

F_4

2022 - 2023 – MPRI

FGLM: Change of the Ordering

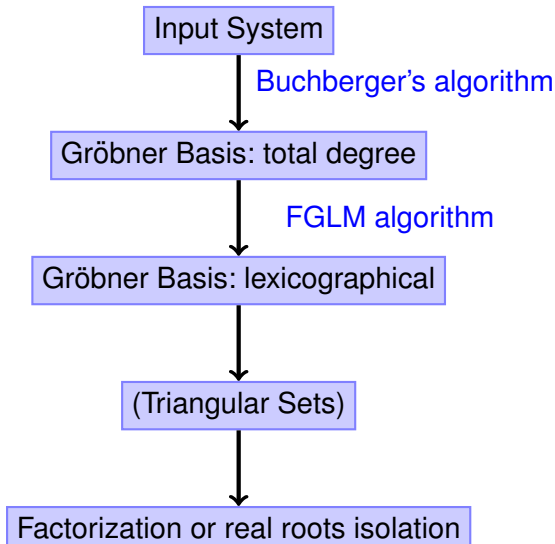
Improve the efficiency

The goal is to speed up the computation of Gröbner basis:

- 1 obtain some speedup for the direct computation Gröbner basis: Buchberger, Magma default (F_4) or any other algorithm.
- 2 compute a Gröbner basis in several steps: the lexicographical ordering is the most useful to compute the solutions but the computation of Gröbner basis for a total degree ordering is much faster.

The **FGLM** algorithm allows us to use linear algebra to perform a change of ordering of a Gröbner basis of a zero dimensional ideal.

Need to use several algorithms



Input of the new algorithm

We assume that the ideal I is **zero-dimensional** and that we know a linear map:

$$\varphi_I : \left(\begin{array}{ccc} \mathbb{K}[x_1, \dots, x_n] & \longrightarrow & \mathbb{K}[x_1, \dots, x_n]/I \\ \mathbf{p} & \longmapsto & \bar{\mathbf{p}} \end{array} \right)$$

which is a normalForm, that is to say satisfies the following conditions:

$$\varphi_I(\mathbf{p}) = \mathbf{0} \text{ if and only if } \mathbf{p} \in I$$

$$\varphi_I(\mathbf{p} \cdot \mathbf{q}) = \varphi_I(\mathbf{p} \cdot \varphi_I(\mathbf{q})) = \varphi_I(\varphi_I(\mathbf{p}) \cdot \varphi_I(\mathbf{q}))$$

$$\varphi \circ \varphi = \varphi$$

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A natural choice is to take $\varphi_I(p) = \text{NormalForm}(p, G, <)$. In that case, the kernel φ_I is exactly the ideal I :

$$\ker(\varphi_I) = I \text{ (Buchberger's Theorem).}$$

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Example

$G_{<_{\text{DRL}}} = [x_1^2 - 3x_2 - x_1 + 1, x_2^2 - 2x_1 + x_2 - 1]$ is a Gröbner basis wrt then monomial ordering DRL with $x_2 > x_1$. Then

$$\varphi : p \longmapsto \text{NORMALFORM}(p, G_{<_{\text{DRL}}})$$

is a linear map and $\ker(\varphi) = I = \text{Id}(G_{<_{\text{DRL}}})$.

We say that p and q are congruent modulo I , written $p \equiv q$, iff $\varphi(p) = \varphi(q)$.

Proposition

Let $I \subset \mathbb{K}[x_1, \dots, x_n]$ be an ideal. Then the congruence modulo I is an equivalence relation on $\mathbb{K}[x_1, \dots, x_n]$.

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An equivalence relation on $\mathbb{K}[x_1, \dots, x_n]$ partitions $\mathbb{K}[x_1, \dots, x_n]$ into a collection of disjoint subsets called equivalence classes.

For any $p \in \mathbb{K}[x_1, \dots, x_n]$, the class of p is the set

$$\bar{p} = \{q \in \mathbb{K}[x_1, \dots, x_n] \mid \varphi(q) = \varphi(p)\}$$

Very often, in the following we will identify \bar{p} and p !

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$$\begin{aligned}\bar{p} + \bar{q} &= \overline{p + q} \\ \bar{p} \times \bar{q} &= \overline{p \times q}\end{aligned}$$

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This is also a Vector space : $\mathbb{K}[x_1, \dots, x_n] / \ker(\varphi) = \mathbb{K}[x_1, \dots, x_n] / I$

Basis of the vector space

Definition (staircase of an ideal)

Let I be an ideal in $\mathbb{K}[x_1, \dots, x_n]$ and $(G, <)$ a Gröbner basis of I , then we define the staircase of G by

$$\mathcal{E}(G) = \{t \in T \mid t \text{ is not reducible by } G\} \text{ sorted wrt } < .$$

We say that it is the canonical basis (wrt G) of the \mathbb{K} -vector space $\mathbb{K}[x_1, \dots, x_n]/I$.

Zero dimensional ideal

Recall that we have a criterion to determine when a system of polynomial equations over $\overline{\mathbb{K}}$ has only **finitely many solutions**:

Theorem

I ideal generated by $\langle f_1, \dots, f_m \rangle$.

G Gröbner basis of I wrt $<$

The algebraic variety $V_{\overline{\mathbb{K}}}(I)$ is finite iff

$\forall i \in \{1, \dots, n\}$ there exists $g_i \in G$ such that $\text{LT}(g_i) = x_i^{k_i}$
or $\{t \in T \mid t \text{ is not reducible by } G\}$ is finite.

Example

$G_{<_{\text{DRL}}} = [x_1^2 - 3x_2 - x_1 + 1, x_2^2 - 2x_1 + x_2 - 1]$ a Gröbner basis wrt a DRL ordering such that $x_2 > x_1$.

Any polynomial

$$f = -x_1^2 - x_2^2 + 7x_1x_2$$

is first reduced wrt $G_{<_{\text{DRL}}}$

$$NF(f, G_{<_{\text{DRL}}}) =$$

And so in the canonical basis \mathcal{B} the polynomial f can be represented by the vector :

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$$\mathcal{E}(G) = \{w_1 = 1, w_2 = x_1, w_3 = x_2, w_4 = x_1 x_2\}$$

$\mathcal{B} = \{\overline{w}_1, \overline{w}_2, \overline{w}_3, \overline{w}_4\}$ is a basis of the \mathbb{K} -vector space $\mathbb{K}[x_1, \dots, x_n]/I$.

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$$\begin{aligned} NF(f, G_{<_{\text{DRL}}}) &= -3x_1 - 2x_2 + 7x_1 x_2 \\ &= -3\overline{w}_2 - 2\overline{w}_3 + 7\overline{w}_4 \end{aligned}$$

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$$[0, -3, -2, 7]$$

Ideal of dimension 0

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Theorem (criterion to determine when a system of polynomial equations over $\overline{\mathbb{K}}$ has only finitely many solutions.)

The algebraic variety $V_{\overline{\mathbb{K}}}(\langle f_1, \dots, f_m \rangle)$ is finite iff $D = \#\mathcal{E}(G) < \infty$. D is the number of solutions (counting with multiplicities), in the algebraic closure, of the polynomial system $[f_1, \dots, f_m]$.

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We denote by $D = \deg(I) = \#\mathcal{E}(G)$ the dimension of the \mathbb{K} -vector space $\mathbb{K}[x_1, \dots, x_n]/I$ (this is also the **degree** of the ideal I).

We assume that:

$$\mathcal{E}(G) = \{w_1 = 1 < w_2 < \dots < w_{\deg(I)}\}$$

What is the expected number of solutions ?

Theorem (Bezout's Bound)

Assume that \mathbb{K} is algebraically closed. Let $I \subset \mathbb{K}[x_1, \dots, x_n]$ be a zero-dimensional ideal generated by $[f_1, \dots, f_n]$ then

$$D = \deg(I) \leq \prod_{i=1}^n \deg(f_i)$$

For instance for n quadratic equations in n variables the bound is 2^n .

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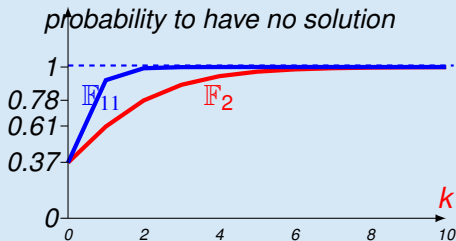
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Theorem (Fusco and Bach)

The probability that a random polynomial system of $n + k$ random equations of degree- d ($d \geq 2$) in n variables over \mathbb{F}_p , has **no solution** is $e^{-p^{-k}}$ (asymptotically)



Example

In $\mathbb{Q}[x_1, x_2]$ the list $G_{<_{\text{DRL}}} = [x_1^2 - 3x_2 - x_1 + 1, x_2^2 - 2x_1 + x_2 - 1]$ is a Gröbner basis wrt a DRL ordering such that $x_2 > x_1$; we try to compute a lexicographical ($x_2 > x_1$) Gröbner basis of $\text{Id}(G)$.

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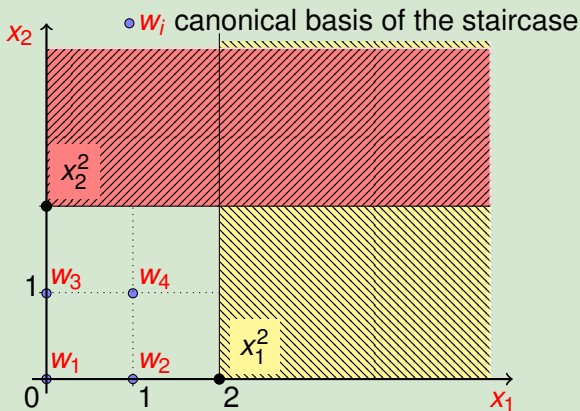
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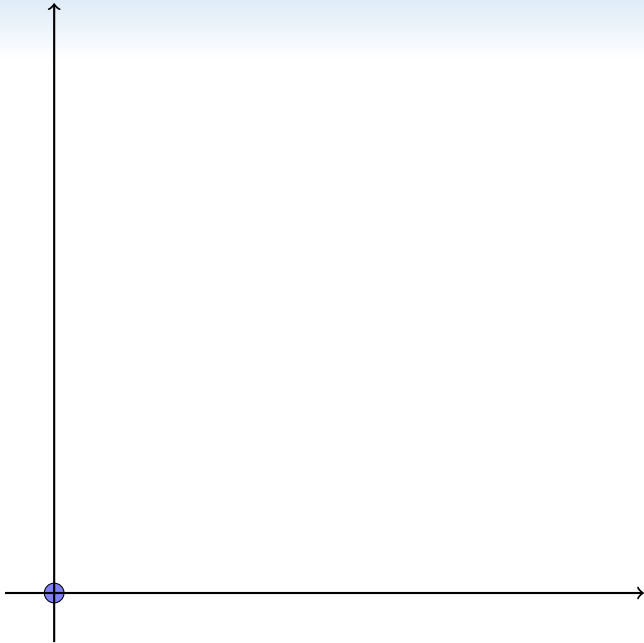
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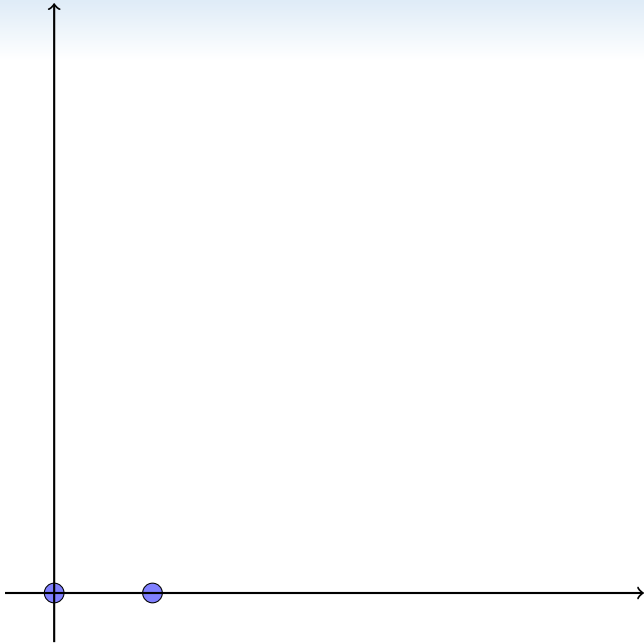
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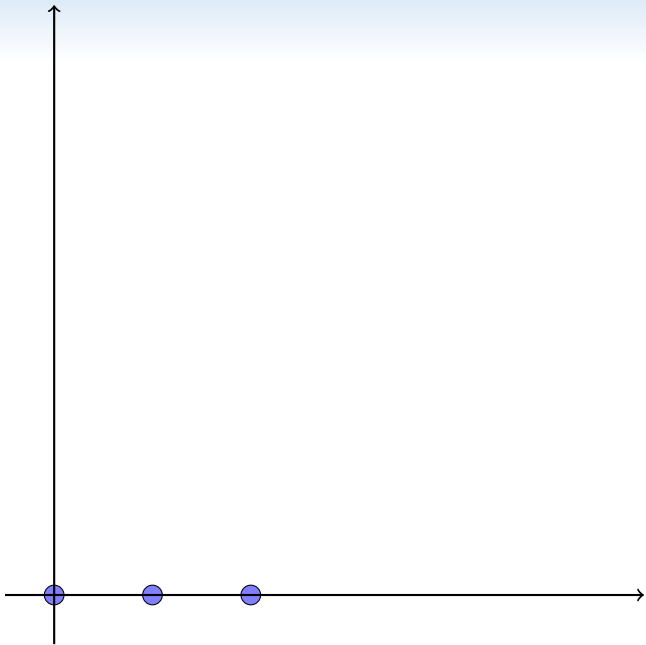
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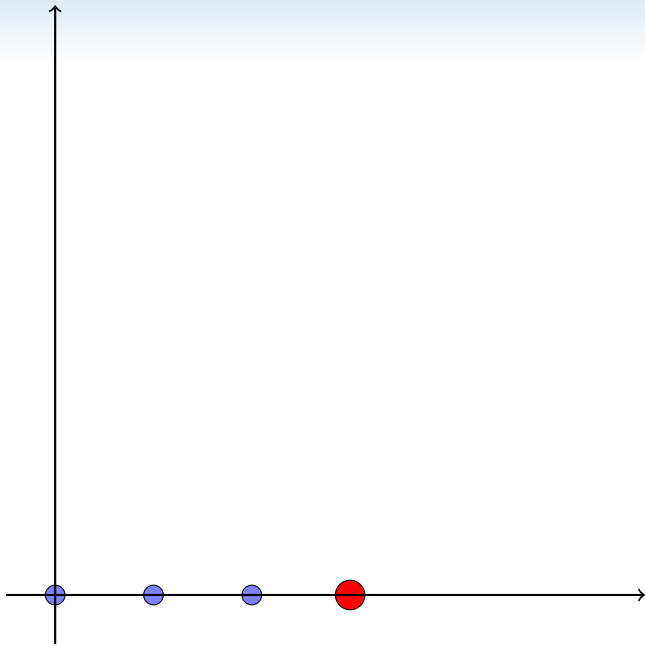


The system has 4 complex roots.

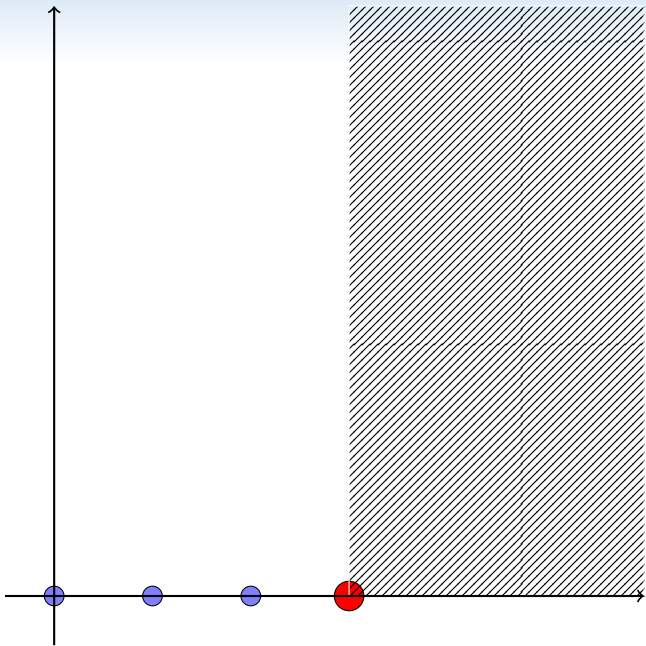




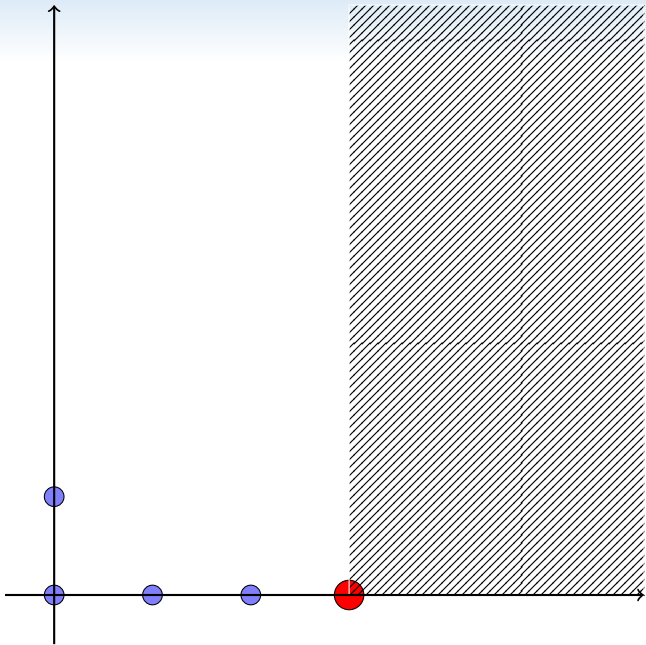




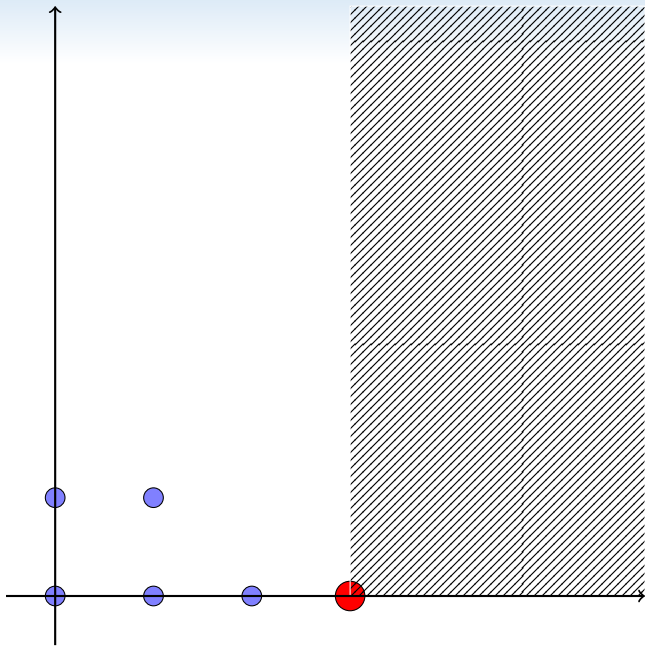
$$g_1 = x^3 + \dots$$



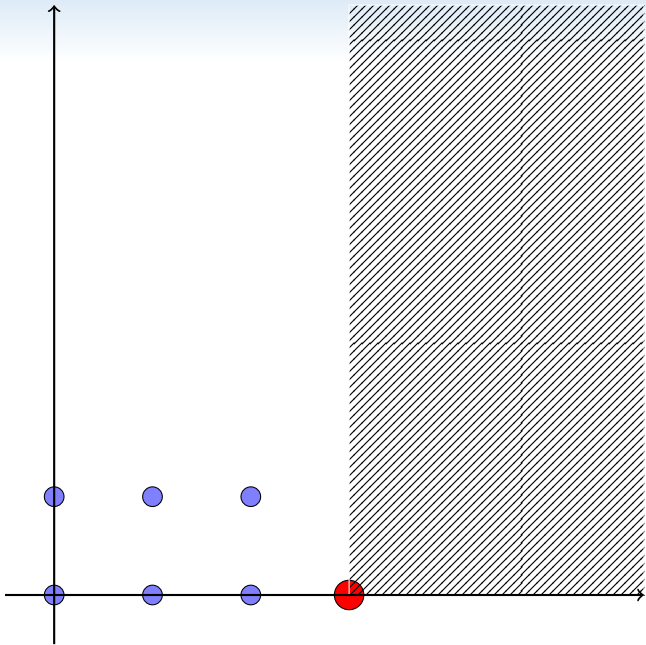
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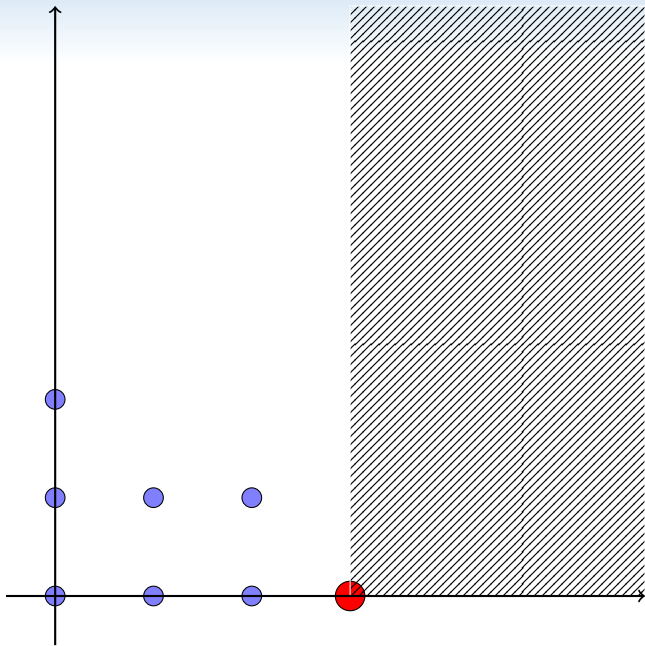
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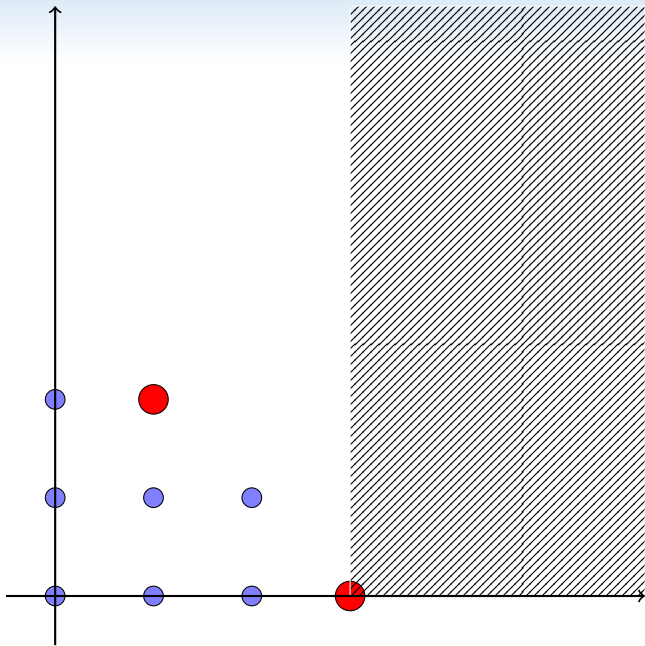
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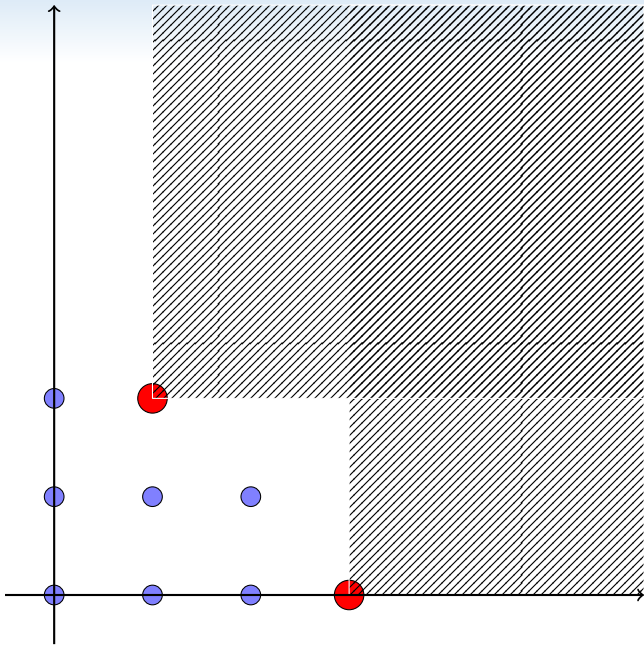


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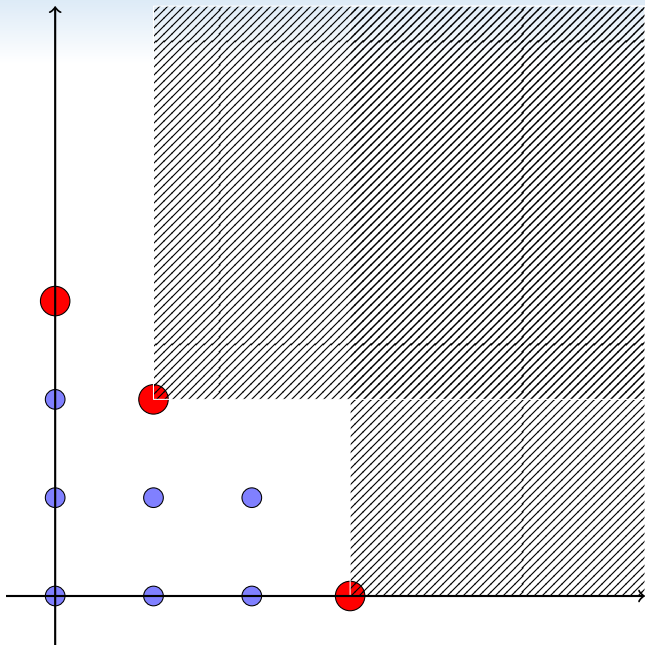
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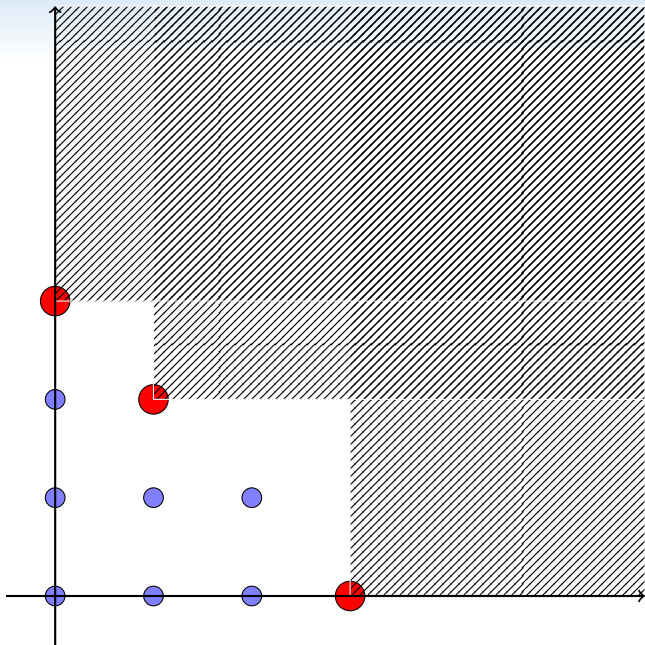
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FGLM algorithm

FGLM=Faugère, Giani, Lazard, Mora, JSC, 1994

Algorithm (FGLM [6])

Input: $<_2$ a monomial ordering and **NF** a normal form.

Output: reduced Gröbner basis I wrt $<_2$

where $I = \{f \in \mathbb{K}[x_1, \dots, x_n] \mid \text{NF}(f) = 0\}$

$L := []$ // list of next terms to study

$S := []$ // the staircase wrt the new ordering $<_2$

$V := []$ // $V = \text{NF}(S)$

$G := [], t := 1$

infinite loop

...

Algorithm (FGLM [6])

...

infinite loop

$v := \text{NF}(t)$ and $s := \#S$ is the number of elements in S .

if $v \in \text{Vect}_{\mathbb{K}}(V)$ then

we can find (λ_i) s.t. $v = \sum_{i=1}^s \lambda_i \cdot V_i$

$$G := G \cup \left[t - \sum_{i=1}^s \lambda_i \cdot S_i \right]$$

else

$S := S \cup [t]$ and $V := V \cup [v]$

$L := \text{Sort}(L \cup [x_i t \mid i = 1, \dots, n], <_2)$

Sort L by increasing order (wrt $<_2$) and

remove duplicates and multiple of $\text{LT}(G)$

if $L = \emptyset$ then

return G

$t := \text{first}(L)$ and remove t from L .

Compute normalForm using linear algebra

We are working in the \mathbb{K} -vector space $\mathbb{K}[x_1, \dots, x_n]/I$ using the canonical basis wrt $<$ (old ordering: G is a Gröbner basis wrt $<$):

$$\mathcal{E}(G) = \{w_1 = 1 < w_2 < \dots < w_{\deg(I)}\}.$$

If $f \in \mathbb{K}[x_1, \dots, x_n]$ we can compute $\text{NF}(f, G) \in \mathbb{K}[x_1, \dots, x_n]/I$ using the FULLREDUCTION algorithm but it is difficult to obtain a precise bound of complexity !

This can be done with linear algebra; more precisely only **matrix vector products**.

Border of an ideal

The staircase $\mathcal{E}(\mathcal{G})$ is stable under division:

Proposition

If $1 \neq e \in \mathcal{E}(\mathcal{G})$ then for all i such that x_i divides e we have $\frac{e}{x_i} \in \mathcal{E}(\mathcal{G})$.

We try to estimate the number of elements in \mathcal{G} with respect to $\deg(I) = D$; to this end we define the border of the staircase:

Definition (Border of a Gröbner basis)

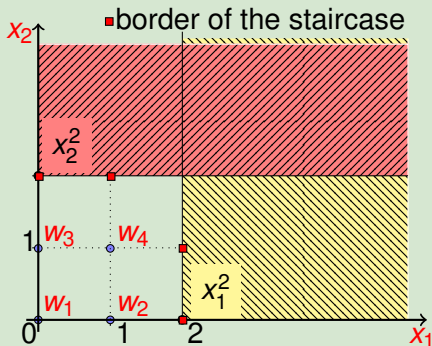
let $\mathcal{E}(\mathcal{G})$ be the canonical basis of $\mathbb{K}[x_1, \dots, x_n] / I$, then the border of \mathcal{G} is:

$$\mathcal{F}(\mathcal{G}) = \{x_i e \mid e \in \mathcal{E}(\mathcal{G}), 1 \leq i \leq n \text{ and } x_i e \notin \mathcal{E}(\mathcal{G})\}$$

Example

$G_{<_{\text{DRL}}} = [x_1^2 - 3x_2 - x_1 + 1, x_2^2 - 2x_1 + x_2 - 1]$ is a Gröbner basis wrt the DRL ordering with $x_2 > x_1$.

border of G : $\mathcal{F}(G) = \{x_i e \mid e \in \mathcal{E}(G), 1 \leq i \leq n \text{ and } x_i e \notin \mathcal{E}(G)\}$



$$\mathcal{F}(G) = \{x_1^2, x_2^2, x_1^2 x_2, x_1 x_2^2\}$$

Proposition

$\dim(I) = 0$, $(G, <)$ a Gröbner basis, then

$$\text{LT}(G) \subset \mathcal{F}(G) \subset \text{LT}(G) \cup \{x_j t' \mid t' \in \mathcal{F}(G) \text{ and } 1 \leq j \leq n\}$$

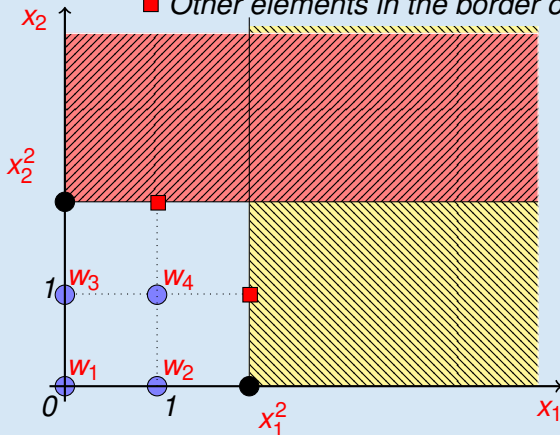
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● Elements in the Gröbner basis

■ Other elements in the border of the staircase



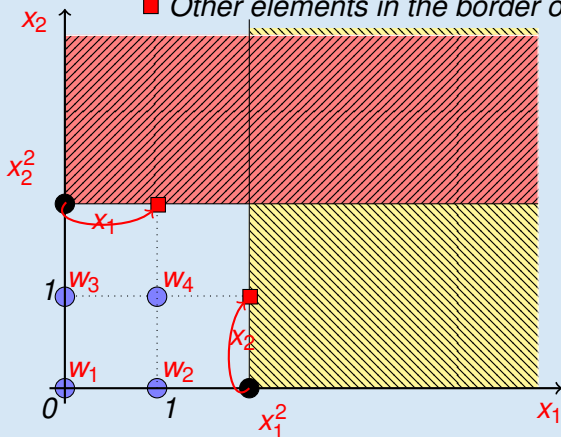
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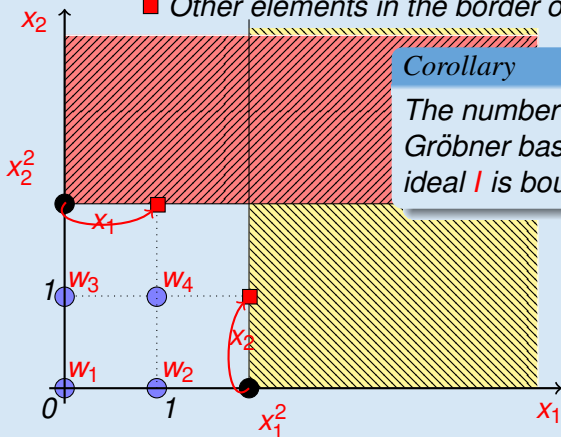
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Corollary

The number of elements of a Gröbner basis of a zero-dimensional ideal I is bounded by $n \deg(I)$.

Computing normal Form using linear algebra

We take advantage of the structure of the vector space to compute in **polynomial time** the normal forms. When running the FGLM algorithm we have to compute $\varphi_I(t)$ in the following case:

Computing normal Form using linear algebra

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- if $t \in \mathcal{E}(G)$ we have $\varphi_I(t) = t$ hence no computation !
- if $t = LT(g)$ for some $g \in G$ (g monic) then $\varphi_I(t) = t - g$
- if $t \in \mathcal{F}(G)$ and $t \notin LT(G)$ then using the previous proposition we have $t = x_j t'$ and since $t' < t$ we have already computed $p = \varphi_I(t')$ and so we have to compute $\varphi_I(t) = \varphi_I(x_j \cdot p)$.

Computing normal Form using linear algebra

We take advantage of the structure of the vector space to compute in **polynomial time** the normal forms. When running the FGLM algorithm we have to compute $\varphi_I(t)$ in the following case:

- if $t \in \mathcal{E}(G)$ we have $\varphi_I(t) = t$ hence no computation !
- if $t = LT(g)$ for some $g \in G$ (g monic) then $\varphi_I(t) = t - g$
- if $t \in \mathcal{F}(G)$ and $t \notin LT(G)$ then using the previous proposition we have $t = x_j t'$ and since $t' < t$ we have already computed $p = \varphi_I(t')$ and so we have to compute $\varphi_I(t) = \varphi_I(x_j \cdot p)$.

Definition (Multiplication by one variable)

For all $1 \leq k \leq n$, consider the following linear map:

$$\phi_i : f \longmapsto \varphi_I(x_i f)$$

In the canonical basis the matrix representation of ϕ_i is the so called multiplication matrix M of size $\deg(I) \times \deg(I)$ such that :

$$M_{i,j}^{(k)} = \text{the coefficient of } w_j \text{ in } \varphi_I(x_k w_j)$$

Example

$$G_{<DRL} = [x_1^2 - 3x_2 - x_1 + 1, x_2^2 - 2x_1 + x_2 - 1]$$

$$\mathcal{E}(G) = \{w_1 = 1, w_2 = x_1, w_3 = x_2, w_4 = x_1 x_2\}$$

We can compute the matrix multiplication by x_1 and x_2 :

$$M^{(1)} = \begin{array}{c|cccc} & x_1 w_1 & x_1 w_2 & x_1 w_3 & x_1 w_4 \\ w_1 & 0 & -1 & 0 & 3 \\ w_2 & 1 & 1 & 0 & 6 \\ w_3 & 0 & 3 & 0 & -4 \\ w_4 & 0 & 0 & 1 & 1 \end{array}$$

$$M^{(2)} = \begin{array}{c|cccc} & x_2 w_1 & x_2 w_2 & x_2 w_3 & x_2 w_4 \\ w_1 & 0 & 0 & 1 & -2 \\ w_2 & 0 & 0 & 2 & 3 \\ w_3 & 1 & 0 & -1 & 6 \\ w_4 & 0 & 1 & 0 & -1 \end{array}$$

Kronecker's delta: $\delta_{i,j} = 1$ if $i = j$ else 0 .

Algorithm Matrix multiplication

Initialisation of the matrices

$\mathcal{E}(G) = \{w_1 = 1 < w_2 < \dots < w_{\deg(l)}\}$ canonical basis wrt G .

$N := []$ // an array of polynomial indexed by T

// and satisfying that for all $t \in T : N[t] = \text{NF}(t, G, <)$

for i from 1 to $\deg(l)$ do

$N[w_i] := w_i$

for each k such that $w_i = x_k w_j$ do

$M_{l,j}^{(k)} := \delta_{l,i}$ for all $l \in \{1, \dots, n\}$

$F := [x_j w_i \text{ pour } j = 1, \dots, n, i = 1, \dots, \deg(l)]$

sort F wrt $<$, remove duplicates and the elements of $\mathcal{E}(G)$.

...

Algorithm (Matrix multiplication)

...

sort F wrt $<$, remove duplicates and the elements of $\mathcal{E}(G)$.

for t in F do

 if t is a strict multiple of some leading term of G then

$t = x_j t'$ with $t' < t$

 We have already computed $N[t'] = \sum_{i=1}^s \mu_i w_i$ with $\mu_i \in K$ and $w_s < t'$

$N[t] = \sum_{i=1}^s \mu_i \text{Col}(M^{(j)}, i) = \sum_{i=1}^{\deg(t)} \lambda_i w_i$

 for each k such that $t = x_k w_l$ for some our un certain l do

$M_{i,j}^{(k)} := \lambda_i$ for all $i \in \{1, \dots, n\}$

 else

 there exists $g = t + \sum_{i=1}^{\deg(t)} \lambda_i w_i$ et $\lambda_i \in K \in G$ such that $t = \text{LT}(g)$

$N[t] := - \sum_{i=1}^{\deg(t)} \lambda_i w_i$

 for each k such that $t = x_k w_j$ for some j do

$M_{i,j}^{(k)} := -\lambda_i$ for all $i \in \{1, \dots, n\}$

return $M^{(k)}$ // matrix multiplication by x_k

Complexity: compute the matrices

Theorem

The previous algorithm computes the matrices $M^{(k)}$ and the complexity is bounded by $O(n \deg(I)^3)$.

Proof.

...



Matrix version of FGLM

We need to have a simple linear procedure to detect linear dependency of vectors in the \mathbb{K} -vectorial space $\mathbb{K}[x_1, \dots, x_n]/I$.

The invertible matrix P represents a change of basis between the old basis

$$\mathcal{E}(G) = \{w_1 = 1 < w_2 < \dots < w_{\deg(I)}\}$$

and the new basis S . That is to say that if $S = [\varepsilon_1, \dots, \varepsilon_{\deg(I)}]$ then at any step of the algorithm we have:

$$S = P \cdot \mathcal{E}(G)$$

At the beginning $S = [w_1]$, and we compute successively the vectors $v = \varphi(x_k w) = M^{(k)} \cdot w$ where v, w are the vectors wrt the basis $\mathcal{E}(G)$:

$$v = \sum_{i=1}^{\deg(I)} v_i \overline{w}_i$$

Matrix version of FGLM

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$$v = \sum_{i=1}^{\deg(I)} v_i \bar{w}_i$$

To test linear independence we can simply compute:

$$\lambda = P \cdot v = \sum_{i=1}^{\deg(I)} \lambda_i \bar{w}_i$$

- 1 if $\lambda_{\#S+1} = \dots = \lambda_{\deg(I)} = 0$ then $v \in \text{Vect}_{\mathbb{K}}(S)$.
- 2 if there exist $k > \#S$ such that $\lambda_k \neq 0$ then $\varepsilon_{\#S+1} := \lambda$ is an **independent vector**. We compute a matrix P' such that:

$$P' \cdot v = {}^T [0, \dots, 0, 1, 0, \dots, 0] = \varepsilon_{\#S+1}$$

Updating the Change of Basis Matrix

Algorithm (UPDATE Update the Change of Basis Matrix)

Input: $s \in \mathbb{N}$, a vector λ and matrix P

Output: a new matrix P'

$k := \min \{j > s \text{ such that } \lambda_j \neq 0\}$

for j from 1 to $\deg(I)$ do

$\alpha := \frac{P_{j,k}}{P_{k,k}}$, $P_{j,k} := P_{s+1,j}$, $P_{s+1,j} := \alpha$

if $\alpha \neq 0$ then

for i from 1 to $\deg(I)$ such that $i \neq s + 1$ do

$P_{i,j} := P_{i,j} - \alpha \lambda_j$

return P

Algorithm Matrix-FGLM

Input: \lt new monomial ordering, $M^{(k)}$ multiplication matrices

$S := [1]$, $V := [w_1]$, $G := []$, $t := (n, 1)$

$L := [(i, 1), i = 1, \dots, (n-1)]$ // (i, j) equivalent to $x_i S[j]$

$P := I_{\deg(I)}$ change of basis matrix between the new basis S and $\mathcal{E}(G)$

infinite loop

$s := \#S$ number of elements in S .

$t = (k, l)$: we compute $v = M^{(k)} \cdot V_l$ and $\lambda = P \cdot v$

if $\lambda_{s+1} = \dots = \lambda_{\deg(I)} = 0$ then

$$G := G \cup \left[x_k S_l - \sum_{i=1}^s \lambda_i \cdot S_i \right]$$

else

$P := \text{UPDATE}(s, \lambda, P)$

$S := S \cup [x_k S_l]$ and $V := V \cup [v]$

$L := \text{Sort}(L \cup [(i, s) \mid i = 1, \dots, n], \lt)$

Sort L wrt \lt_2 and remove duplicates and multiple of $\text{LT}(G)$

if $L = \emptyset$ then return G

$t := \text{first}(L)$ and removes t from L

Example

$$n = 2 \text{ and } G_{<_{\text{DRL}}} = [x_1^2 - 3x_2 - x_1 + 1, x_2^2 - 2x_1 + x_2 - 1]$$

$$\mathcal{E}(G) = \{w_1 = 1, w_2 = x_1, w_3 = x_2, w_4 = x_1 x_2\}$$

Lexicographical ordering with $x_2 > x_1$.

Multiplication matrices by x_1 and x_2 :

$$M^{(1)} = \begin{array}{c} w_1 \\ w_2 \\ w_3 \\ w_4 \end{array} \begin{array}{c} x_1 w_1 \\ x_1 w_2 \\ x_1 w_3 \\ x_1 w_4 \end{array} \begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \end{array} \begin{array}{c} -1 \\ 1 \\ 3 \\ 0 \end{array} \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} \begin{array}{c} 3 \\ 6 \\ -4 \\ 1 \end{array} \left| \right.$$

$$M^{(2)} = \begin{array}{c} w_1 \\ w_2 \\ w_3 \\ w_4 \end{array} \begin{array}{c} x_2 w_1 \\ x_2 w_2 \\ x_2 w_3 \\ x_2 w_4 \end{array} \begin{array}{c} 0 \\ 0 \\ 1 \\ 0 \end{array} \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} \begin{array}{c} 1 \\ 2 \\ -1 \\ 0 \end{array} \begin{array}{c} -2 \\ 3 \\ 6 \\ -1 \end{array} \left| \right.$$

$L := [(2, 1)]$, $S := [1]$, $V := [w_1]$, $G := []$, $t := (1, 1)$ represent the monomial $x_1 \cdot S_1 = x_1$, $P := I_4$

Example

Step 1: Since $t = (1, 1)$, we compute $v := M^{(1)} \cdot V_1 = M^{(1)} \cdot 1 = w_2$
and $\lambda = P \cdot v = w_2 = {}^T [0, 1, 0, 0]$

Hence $\lambda_2 \neq 0$, $S := [1, x_1]$, $V := [w_1, w_2]$ and the matrix P is left unchanged.

We update L : $L := [(1, 2), (2, 1), (2, 2)]$.

Example

Step 2: Since $t = (1, 2)$, we compute $v := M^{(1)} \cdot V_2 = M^{(1)} \cdot w_2 =^T [-1, 1, 3, 0]$

and $\lambda = P \cdot v =^T [-1, 1, 3, 0] := V_3$

since $\lambda_3 \neq 0$, $S := [1, x_1, x_1^2]$, $V := [w_1, w_2,^T [-1, 1, 3, 0]]$, then

$$P := \begin{bmatrix} 1 & 0 & 1/3 & 0 \\ 0 & 1 & -1/3 & 0 \\ 0 & 0 & 1/3 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

We update $L : L := [(1, 3), (2, 1), (2, 2), (2, 3)]$.

Example

Step 3: $t = (1, 3)$. We compute $v := M^{(1)} \cdot V_3 = M^{(1)} \cdot^T [-1, 1, 3, 0] =^T [-1, 0, 3, 3]$

and

$$\lambda = P \cdot v =^T [0, -1, 1, 3]$$

Since $\lambda_4 \neq 0$, $S := [1, x_1, x_1^2, x_1^3]$, $V := [w_1, w_2, V_3,^T [-1, 0, 3, 3]]$, and then

$$P := \begin{bmatrix} 1 & 0 & 1/3 & 0 \\ 0 & 1 & -1/3 & 1/3 \\ 0 & 0 & 1/3 & -1/3 \\ 0 & 0 & 0 & 1/3 \end{bmatrix}$$

We update $L := [(1, 4), (2, 1), (2, 2), (2, 3), (2, 4)]$.

Example

Step 4: $t = (1, 4)$. We compute $v := M^{(1)} \cdot V_4 = M^{(1)} \cdot^T [-1, 0, 3, 3] =^T [9, 17, -12, 6]$

then $\lambda = P \cdot v =^T [5, 23, -6, 2]$

since $\lambda_5 = 0$, we find a polynomial $G := [x_1^4 - 2x_1^3 + 6x_1^2 - 23x_1 - 5]$
and now $L := [(2, 1), (2, 2), (2, 3), (2, 4)]$.

Example

Step 5: $t = (2, 1)$. We compute $v := M^{(2)} \cdot V_1 = M^{(2)} \cdot w_1 = w_3$
and $\lambda = P \cdot w_3 = {}^T \left[\frac{1}{3}, \frac{-1}{3}, \frac{1}{3}, 0 \right]$

since $\lambda_5 = 0$, $G := [x_1^4 - 2x_1^3 + 6x_1^2 - 23x_1 - 5, x_2 - \frac{1}{3}x_1^2 + \frac{1}{3}x_1 - \frac{1}{3}]$,
by removing multiples of $\text{LT}(G_2) = x_2$, we obtain $L := \square$
and the FGLM algorithm stops.

Theorem

The complexity (number of operations in \mathbb{K}) of the FGLM and the matrix FGLM algorithms is bounded by $O(n \deg(I)^3)$. Moreover, the result is a Gröbner basis.

Proof.

...



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...



Remark

Let V be the algebraic variety associated to the ideal $\langle f_1, \dots, f_m \rangle$ in n variables. When the system has a finite number of solutions:

- 1 We can compute $P(x_n)$ the smallest polynomial in a lexicographical Gröbner basis as the minimal polynomial P of the matrix $M^{(n)}$.
- 2 The projection of V on $\mathbb{K}[x_n]$ is thus the eigenvectors of the matrices $M^{(n)}$.

Application of polynomial system solving: Algebraic Crypto

- Evaluate the security of existing cryptosystems.
 - Investigating the security of extensively used cryptographic standards – such as AES, SHA, RSA and new post-quantum crypto systems – against the most powerful attacks is a **permanent concern**.

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 - Investigating the security of extensively used cryptographic standards – such as AES, SHA, RSA and new post-quantum crypto systems – against the most powerful attacks is a **permanent concern**.
 - Any progress in the cryptanalysis of such standards could have a **huge impact**, from a scientific and also economical point of view.
 - *General* methods have been proposed: linear cryptanalysis, differential cryptanalysis, ...
- ☞ describe another *general method* : Algebraic Cryptanalysis .

Algebraic cryptanalysis

In this talk \longrightarrow another general method: **Algebraic Cryptanalysis**

Principle

- Model a cryptosystem as a set of algebraic equations
- Try to solve this system (or estimate the difficulty of solving it)

Algebraic Cryptanalysis: model

Very simple **idea**:

1 Model a cryptosystem as a set of algebraic equations:

$$\mathcal{S} \begin{cases} f_1(x_1, \dots, x_n) = 0 \\ \dots \\ f_m(x_1, \dots, x_n) = 0 \end{cases}$$

where all the $f_i \in \mathbb{K}[x_1, \dots, x_n]$ and \mathbb{K} is a finite field (for instance $\mathbb{K} = \mathbb{F}_2$).

Algebraic Cryptanalysis: solving

2 Evaluate the difficulty of **solving** the corresponding algebraic system \mathcal{S} .

$$V_{\mathbb{K}} = \{z = (z_1, \dots, z_n) \in \mathbb{K}^n \mid f_1(z) = \dots = f_m(z) = 0\}$$

→ **General Method**: new criteria to evaluate the security.

Approach

Difficulties

- Model a cryptosystem as a set of algebraic equations
“universal” approach
(PoSSo is NP-Hard))
several models are possible !!!
- Solving
 - Minimize the number of variables/degree
 - Maximize the number of equations

Tool

Gröbner Bases computations:
Algorithms + Complexity

Specificity

Solving algebraic systems :

- Huge systems
- Sparse/structured systems
- Try to predict accurately the complexity of computing Gröbner basis for particular instances.

A Zero-Dimensional Gröbner Basis for AES-128 Buchmann, J. and Pyshkin, A. and Weinmann, R.-P.

Abstract. We demonstrate an efficient method for computing a Gröbner basis of a zero-dimensional ideal describing the key-recovery problem from a single plaintext/ciphertext pair for the full AES-128. This Gröbner basis is relative to a degree-lexicographical order. We investigate whether the existence of this Gröbner basis has any security implications for the AES.

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3.2 The S-Box

The S-Box used in Rijndael can be interpolated as a sparse polynomial over F :

$$\sigma : F \rightarrow F, \quad x \mapsto 05x^{254} + 09x^{253} + F9x^{251} + 25x^{247} + F4x^{239} + B5x^{223} + B9x^{191} + 8Fx^{127} + 63 \quad (2)$$

Crypto example: AES

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3.5 Choosing a Suitable Variable Order

The plaintext and ciphertext polynomials simply are of the form

$$x_{i,0} + p_i \quad p_i \in F, 0 \leq i \leq 15 \quad (13)$$

respectively

$$x_{i,0} + c_i \quad c_i \in F, 0 \leq i \leq 15. \quad (14)$$

Let \mathcal{A} be the union of the left-hand side of equations (9), (10) and (12) for all rounds $1 \leq j \leq 10$ as well as the plaintext and ciphertext polynomials. Ordering the variables as follows makes all head terms pairwise prime:

1. plaintext variables: $x_{0,0} < \dots < x_{15,0}$
2. ciphertext variables: $x_{0,10} < \dots < x_{15,10}$
3. key variables of all rounds in natural order: $k_{0,0} < k_{1,0} < \dots < k_{15,10}$
4. intermediate state variables in their natural order

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The degree lexicographical term order with the above variable order will be in the following be referred to as $<_{\mathcal{A}}$. By Theorem 1, the set of polynomials \mathcal{A} is a Gröbner basis relative to this term order! Moreover, checking Lemma 1 we verify that this ideal is zero-dimensional.

Crypto example: AES

This result is sufficient to give a bound on the complexity of the Gröbner basis conversion using FGLM. The following theorem is a slightly rephrased version of Theorem 5.1 in [12]:

Theorem 2. *Let F be a finite field and $R = F[x_1, \dots, x_n]$. Furthermore $G_1 \subset R$ is the Gröbner basis relative to a term order $<_1$ of an ideal I , and $D = \dim(R/I)$. We can then convert G_1 into a Gröbner basis G_2 relative to a term order $<_2$ in $O(nD^3)$ field operations.*

$$\dim(R/\mathcal{A}) = 254^{200} \approx 2^{1598}$$

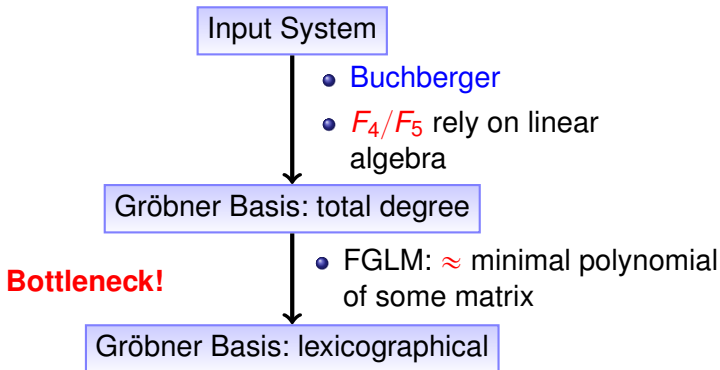
Fast FGLM

joint work with C. Mou

Fast FGLM: High Performance Algorithm and Implementation

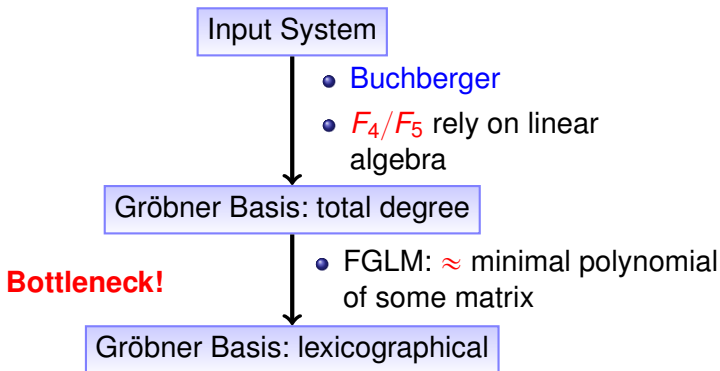
Fast FGLM - Problem

with C. Mou



Fast FGLM - Problem

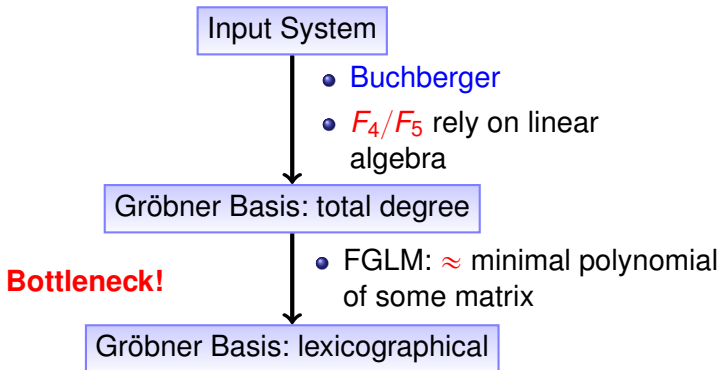
with C. Mou



Magma	MinRank(9,7,4)	MinRank(9,8,5)	Random(14, 2)	Random(15, 2)
D	4116	14112	2^{14}	2^{15}
Step 1	208.1s	3343.5s	7832.4s	74862.9s
Step 2	1360.4s	> 1 day	84374.6s	> 15 days

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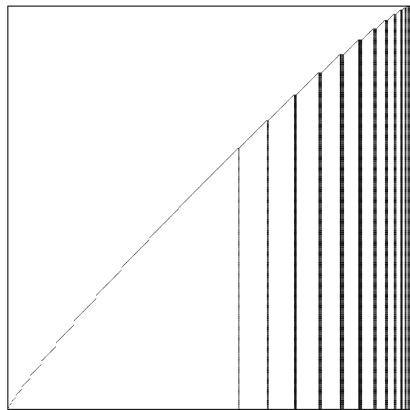
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Goal: a faster algorithm for the change of ordering

Key observation 1

with C. Mou

T_1, \dots, T_n are sparse, especially T_1 .



T_1 for Random(3, 10): 1000×1000 , 6.86%

$$T_i \times v = \text{NormalForm}(x_i \times v)$$

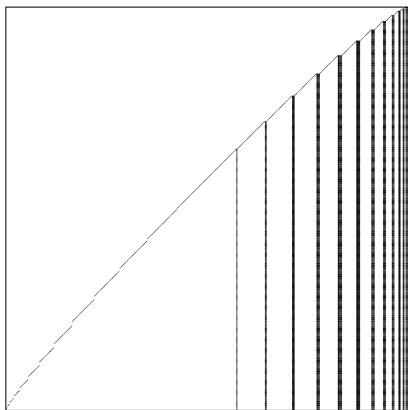
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D	4096	34940	41580
Sparsity	3.4%	1.0%	16%
	Random(3, 14)	Random(3, 40)	
D	2744	64000	
Sparsity	4.2%	1.6%	

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Theorem (Faugère, Mou)

n is fixed. For generic polynomial systems of degree d :

$$\% \text{ of nonzero entries } \underset{d \rightarrow \infty}{\sim} \sqrt{\frac{6}{\pi}} \frac{1}{d n^{\frac{1}{2}}}$$

Key observation 2

The cost of a matrix/vector multiplication $T \times v$ is $\#T \ll D^2$

Any polynomial $\sum_{\mathbf{s}} c_{\mathbf{s}} \mathbf{x}^{\mathbf{s}}$ in the Gröbner basis is a minimal relation:

$$\sum_{\mathbf{s}} c_{\mathbf{s}} T_1^{s_1} \cdots T_n^{s_n} \mathbf{1} = 0.$$

Define a n -dimensional mapping $E : \mathbb{Z}_{\geq 0}^n \rightarrow \mathbb{K}$ as

$$\Psi : (s_1, \dots, s_n) \mapsto \langle T_1^{s_1} \cdots T_n^{s_n} \mathbf{1}, \mathbf{r} \rangle \quad \mathbf{r} \text{ random vector.}$$

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Find **minimal recurrence relation** of Ψ \rightsquigarrow can be found using BMS (Berlekamp-Massey-Sakata from **Coding Theory**)

Multi-dimensional generalization of Berlekamp–Massey algorithm

[Sakata 1988 & 1990; Saints and Heegard 2002]

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Multi-dimensional generalization of Berlekamp–Massey algorithm

[Sakata 1988 & 1990; Saints and Heegard 2002]

Recent results:

- *Linear Algebra for Computing Gröbner Bases of Linear Recursive Multidimensional Sequences*, [Berthomieu, F. 2015]
- *A Polynomial-Division-based Algorithm for Computing Linear Recurrence Relations*, [Berthomieu, F. 2018]

Easy case: Shape position case

Assume that I is in shape position:

Shape position [Becker, Mora, Marinari, and Traverso 1994]

Ideal $I \subset \mathbb{K}[x_1, \dots, x_n]$ is **in shape position** if its Gröbner basis w.r.t. **LEX** ($x_1 < \dots < x_n$) is of the form

$$[f_1(x_1), x_2 - f_2(x_1), \dots, x_n - f_n(x_1)].$$

Easy case: Shape position case

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Recover f_1 : Wiedemann algorithm

Construct $s = [\langle r, T_1^i \mathbf{1} \rangle : i = 0, \dots, 2D - 1]$, with r a random vector



Compute \tilde{f}_1 from s via **Berlekamp–Massey** algorithm



Check $\deg(\tilde{f}_1) = D$

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Recover f_2, \dots, f_n : constructing linear equations

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where $T' = T_1^t$ is the transpose matrix

We compute only **one time** the sequence of vectors

$$\mathbf{v}_0 = \mathbf{r}, \mathbf{v}_1 = T' \mathbf{r}, \mathbf{v}_2 = T'^2 \mathbf{r}, \dots, \mathbf{v}_{2D-1} = T'^{2D-1} \mathbf{r} \text{ using}$$

$$\mathbf{v}_{i+1} = T' \times \mathbf{v}_i$$

so that $\mathbf{s} = [\langle \mathbf{r}, T_1^j \mathbf{1} \rangle = \langle T'^j \mathbf{r}, \mathbf{1} \rangle = \langle \mathbf{v}_j, \mathbf{1} \rangle : j = 0, \dots, 2D-1]$

Shape position case

Solve: $H c_j = b$ with $c_j = {}^t [c_{j,0}, \dots, c_{j,D-1}]$

$$H = \begin{bmatrix} \langle \mathbf{v}_0, \mathbf{1} \rangle & \langle \mathbf{v}_1, \mathbf{1} \rangle & \cdots & \langle \mathbf{v}_{D-1}, \mathbf{1} \rangle \\ \langle \mathbf{v}_1, \mathbf{1} \rangle & \langle \mathbf{v}_2, \mathbf{1} \rangle & \cdots & \langle \mathbf{v}_D, \mathbf{1} \rangle \\ \vdots & \vdots & \ddots & \vdots \\ \langle \mathbf{v}_{D-1}, \mathbf{1} \rangle & \langle \mathbf{v}_D, \mathbf{1} \rangle & \cdots & \langle \mathbf{v}_{2D-2}, \mathbf{1} \rangle \end{bmatrix}$$

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Construction of $\langle (T_1^t)^j \mathbf{r}, T_1 \mathbf{1} \rangle$ is also free: \mathbf{v} is also free.

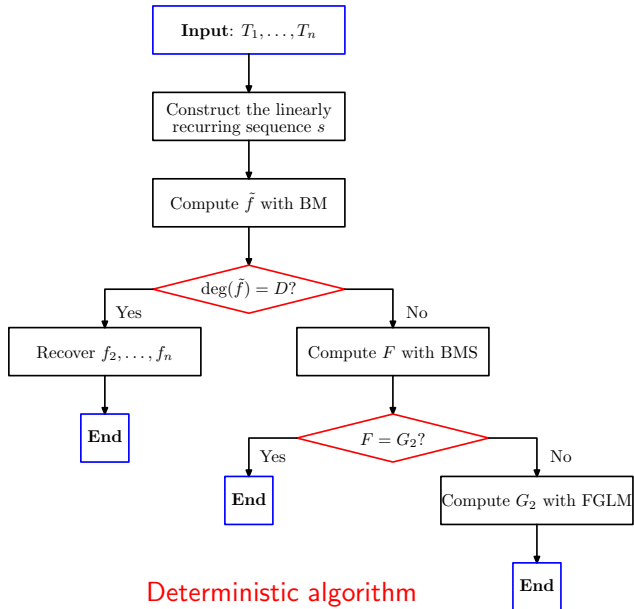
Shape position case

Total complexity for ideals in shape position

$O(D(N_1 + n \log^2(D)))$: $N_1 = \#T' = \#T_1$ the number of nonzero entries in T_1

- compared with $O(nD^3)$ for FGLM
- computing the minimal polynomial of T_1 .

General Algorithm



Efficient Implementation

- Preliminary implementation of the BMS-based method for the general case in **Magma**.
- Shape position case: first has been implemented in **C** over fields of characteristic **0** and finite fields.
- We report also a new **SSE/multicore** implementation.

SSE 4.1 dotproduct fast implementation

16 bits implementation - Intel

Main operation: $\mathbf{y} := T_1 \mathbf{x}$

The matrix vector product is equivalent to compute several **dot products**:

$$\langle \mathbf{x}, \mathbf{y} \rangle = \sum_{i=1}^D x_i y_i \pmod{p}$$

- lazy reduction: we compute the modulo p only at the end
- using 128 bits registers `xmm0-15` that is to say 8 16bits words.
- Using **SSE** instructions we can perform 8 16-bits multiplications simultaneously !
- unrolling the loop we perform **32** multiplications in **one** loop.

Multi-core implementation

Two **parallel** versions:

- Using **Openmp**
- Using **pthread**s

☞ have to rewrite the generation of the matrix T_1 !

Comparing original C-code (Issac 2011) and the new code:

	D	%	Magma	Singular	New	New+SSE
Katsura 12	4096	21.2%	1408s	2623.5s	18.1s	0.73s

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Random(n=3,d=19)	6859	3.50%	1084s	8248s	15.3s	0.74s

Linear Algebra

Idea of the Algorithms

Solve the following systems:

$$S_1 \begin{cases} 123 - 7x^2 + 22xy - 94y^2 = 0 \\ 11 - 62xy - 73y^2 = 0 \\ -4 - 5x^2 + 31xy + 40y^2 = 0 \end{cases}$$

and

$$S_2 \begin{cases} -20 - 15x^2 - 59xy - 96x + 72y^2 \\ 132 - 90x^2 + 43xy + 92x - 91y^2 \\ 5 + 11x^2 + 12xy + 13x - 17y^2 \end{cases}$$

Computing Gröbner Bases: example

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F_4

F_4

Matrix representation of polynomials

Definition

If $F = [f_1, \dots, f_m]$ is a vector of m polynomials and $<$ an admissible ordering, $T_{<}(F) = [t_1, \dots, t_j]$ the monomials in the support of F sorted for $<$. The matrix representation of $M_{T_{<}(F)}(F)$ wrt F is:

$$M(F) = \begin{array}{c} f_1 \\ f_2 \\ f_3 \end{array} \begin{array}{c} \left| \begin{array}{ccc} \dots & \dots & \dots \\ \dots & \dots & \dots \\ \dots & \dots & \dots \end{array} \right| \begin{array}{c} t_1 \\ t_2 \\ t_3 \end{array} \end{array}$$
$$M(F)_{f_i, t_j} = \text{coeff}(f_i, t_j)$$

Moreover, $M(F)$ satisfies the following equation:

$$F = M(F) \cdot T_{<}(F)$$

Polynomial representation of a matrix

Definition

If M is a matrix of size $l \times m$ with coefficients in \mathbb{K} and $X = [t_1, \dots, t_m]$ is a vector of terms, then the **polynomial representation** of M wrt X is the vector of l polynomials given by:

$$F = M \cdot X$$

Example (Cyclic 4 Problem)

The monomial ordering is **DRL**

$$F = \left[\begin{array}{l} f_1 = abcd - 1, f_2 = abc + abd + acd + bcd, \\ f_3 = ab + bc + ad + cd, f_4 = a + b + c + d \end{array} \right]$$

The matrix representation of $F_1 = [f_3, bf_4, df_4]$ is:

$$A_1 = M(F_1) = \begin{array}{l} df_4 \\ f_3 \\ bf_4 \end{array} \left| \begin{array}{ccccccc} ab & b^2 & bc & ad & bd & cd & d^2 \\ 0 & 0 & 0 & 1 & 1 & 1 & 1 \\ 1 & 0 & 1 & 1 & 0 & 1 & 0 \\ 1 & 1 & 1 & 0 & 1 & 0 & 0 \end{array} \right|$$

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$$A_1 = M(F_1) = \begin{array}{l} df_4 \\ f_3 \\ bf_4 \end{array} \left| \begin{array}{cccccc} ab & b^2 & bc & ad & bd & cd & d^2 \\ & & & 1 & 1 & 1 & 1 \\ 1 & & 1 & 1 & & 1 & \\ 1 & 1 & 1 & & 1 & & \end{array} \right|$$

Macaulay matrix

Definition (Macaulay matrix [8])

Let $F = [f_1, \dots, f_m]$ a vector of m polynomials and d a non negative integer then the **Macaulay matrix** in degree d of F $\mathcal{M}_d^{\text{acaulay}}(F)$, is the matrix representation of

$$F^{(d)} = [t_j \cdot f_i \mid 1 \leq i \leq m \text{ and } t_j \in T \text{ with } \deg(t_j) \leq d - \deg(f_i)]$$

$$\mathcal{M}_d^{\text{acaulay}}(F) = M(F^{(d)}) = \begin{array}{ccc|ccc} & & & m_1 & m_2 & m_3 \\ t_1 f_1 & \left| \begin{array}{ccc} \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots \end{array} \right. & & & \\ t_2 f_2 & & & & & \\ \cdots & & & & & \end{array}$$

Echelon form of a matrix

The basis operation is to compute a row echelon form of matrix; this will be the most costly operation.

Definition

If $M(F)$ is the matrix representation of a vector of polynomials F we denote by $\widetilde{M(F)}$ the Gaussian elimination of $M(F)$ (without pivoting the columns of the matrix).

We extend this definition to polynomials:

Definition

Let $F \subset \mathbb{K}[x_1, \dots, x_n]$ and $<$ a monomial ordering. We denote by \tilde{F} the polynomial representation of $\widetilde{M(F)}$. We say that \tilde{F} is the echelon form of F (or a Gaussian elimination) wrt $<$.

Example

The matrix representation of $F_1 = [f_3, bf_4, df_4]$ is:

$$A_1 = M(F_1) = \begin{array}{c} df_4 \\ f_3 \\ bf_4 \end{array} \left| \begin{array}{ccccccc} ab & b^2 & bc & ad & bd & cd & d^2 \\ & & & 1 & 1 & 1 & 1 \\ 1 & & 1 & 1 & & 1 & \\ 1 & 1 & 1 & & 1 & & \end{array} \right|$$

Example

The matrix representation of $F_1 = [f_3, bf_4, df_4]$ is:

$$\tilde{A}_1 = \begin{array}{c} df_4 \\ f_3 \\ bf_4 \end{array} \left| \begin{array}{ccccccc} ab & b^2 & bc & ad & bd & cd & d^2 \\ & & & 1 & 1 & 1 & 1 \\ 1 & & 1 & & -1 & & -1 \\ & 1 & & & 2 & & 1 \end{array} \right|$$

Example

The polynomial representation of:

$$\tilde{A}_1 = \begin{array}{l} df_4 \\ f_3 \\ bf_4 \end{array} \left| \begin{array}{ccccccc} ab & b^2 & bc & ad & bd & cd & d^2 \\ & & & 1 & 1 & 1 & 1 \\ 1 & & 1 & & -1 & & -1 \\ & 1 & & & 2 & & 1 \end{array} \right|$$

$$\tilde{F}_1 = \left[\begin{array}{l} f_5 = ad + bd + cd + d^2, \\ f_6 = ab + bc - bd - d^2, \\ f_7 = b^2 + 2bd + d^2 \end{array} \right]$$

Macaulay method

The idea of using linear algebra to solve polynomial systems [date back to Macaulay](#).

Macaulay matrix is a generalization of the [Sylvester](#) matrix [7] (the matrix involved in the computation of the resultant of **2** polynomials).

The link between the computation of a truncated **d** -Gröbner basis is given by the following theorem of Lazard:

Theorem (Lazard)

If $F = \{f_1, \dots, f_m\}$ is a set of homogeneous polynomials then

$\mathcal{M}_d^{\text{macaulay}}(F)$ is a (non reducible) **d** -Gröbner basis of F .

If $F = \{f_1, \dots, f_m\}$ is a set of polynomials, then there exists **$d > 0$** such that $\mathcal{M}_d^{\text{macaulay}}(F)$ is a Gröbner basis of F .

Macaulay bound

Theorem (Macaulay bound)

Let $F = \{f_1, \dots, f_m\}$ is a set of homogeneous polynomials which is a *regular sequence*. We define

$$D = 1 + \sum_{i=1}^m (\deg(f_i) - 1)$$

then $\widetilde{\mathcal{M}}_D^{\text{macaulay}}(F)$ is a (non reduced) Gröbner basis of F .

Regular sequence I

We consider the Macaulay matrix of $F = [f_1, \dots, f_m]$.

If the Macaulay matrix is singular \longleftrightarrow the rows of the matrix are not independent.

Moreover, each row of the matrix is a product $t \times f$ where t is a term and $f \in F$; the linear dependence can be expressed by

$\sum_{f \in F, t \in T} \lambda_{t,f} t f = 0$ or equivalently by grouping terms:

$$\sum_{i=1}^m g_i f_i = 0 \quad (1)$$

where g_i are polynomials in $\mathbb{K}[x_1, \dots, x_n]$. We say that (g_1, \dots, g_m) is a **syzygy**. The relation (5) can be rewritten:

$$g_1 f_1 = 0 \text{ modulo } \text{Id}(f_2, \dots, f_m) \quad (2)$$

in other words it is a **zero divisor** (if $g_1 \neq 0$).

Regular sequence II

A linear system is non singular if one cannot find a non zero linear combination:

$$\sum_{i=1}^m \lambda_i f_i = 0 \text{ with } \lambda_i \in \mathbb{K} \quad (3)$$

For algebraic systems: it is **not possible** to avoid non zero relations (5) :

$$f_i f_j - f_j f_i = 0 \quad (4)$$

We say that it is a trivial syzygy.

Regular sequence I

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$$g_1 f_1 = 0 \text{ modulo } \text{Id}(f_2, \dots, f_m) \quad (6)$$

in other words it is a **zero divisor** (if $g_1 \neq 0$).

Regular sequence II

A linear system is non singular if one cannot find a non zero linear combination:

$$\sum_{i=1}^m \lambda_i f_i = 0 \text{ with } \lambda_i \in \mathbb{K} \quad (7)$$

For algebraic systems: it is **not possible** to avoid non zero relations (5) :

$$f_i f_j - f_j f_i = 0 \quad (8)$$

We say that it is a trivial syzygy.

Regular sequence III

Definition (Regular Sequence)

Algebraic definition: the system (f_1, \dots, f_m) of homogeneous polynomials is **regular** if for all $i = 1, \dots, m$ and g such that

$$g \cdot f_i \in \langle f_1, \dots, f_{i-1} \rangle$$

then g is also in $\langle f_1, \dots, f_{i-1} \rangle$.

Geometric definition: the system (f_1, \dots, f_m) of homogeneous polynomials is **regular** if for all $i \in \{1, \dots, m\}$, the **dimension** of $\langle f_1, \dots, f_i \rangle$ is $n - i$.

We say that the sequence (f_1, \dots, f_m) is regular.

The sequence (f_1, \dots, f_m) of affine polynomials is regular if the sequence (f_1^h, \dots, f_m^h) is regular (f_i^h is the highest homogeneous part of f_i).

Regular sequence IV

Remark

Another characterization of regular sequences: there is no relation

$$\sum_i g_i \cdot f_i = 0 \text{ with } g_i \in \mathbb{K}[x_1, \dots, x_n]$$

except the relations induced by the trivial syzygies $f_i f_j = f_j f_i$.

Remark

From the geometric definition: there is no regular sequence when $m > n$.

Characterizations of Gröbner Bases

Characterizations of Gröbner Bases

Useful characterizations of Gröbner bases.

Definition (*t*-representation)

Let $P = [p_1, \dots, p_k]$ be a finite subset of $\mathbb{K}[x_1, \dots, x_n]$, $0 \neq f \in \mathbb{K}[x_1, \dots, x_n]$, and $t \in T$. Assume that there exists $(g_1, \dots, g_k) \in \mathbb{K}[x_1, \dots, x_n]^k$ such that:

$$f = \sum_{i=1}^k g_i p_i$$

We say that it is a *t*-representation of f wrt P if $t \geq \text{LT}(g_i p_i)$ for all $1 \leq i \leq k$. We denote by $f = O_P(t)$ this property.

We note $f = o_P(t)$ when there exists $t' \in T$ such that $t' < t$ and $f = O_P(t')$.

Characterizations of Gröbner Bases

Proposition

If f, g are polynomials and t is a term, P a finite subset of polynomials, then

$$f = O_P(t) \quad g = O_P(t) \quad \text{implies} \quad f + g = O_P(t)$$

$$f = o_P(t) \quad g = o_P(t) \quad \text{implies} \quad f + g = o_P(t)$$

$$f = O_P(t) \quad u \in T \quad \text{implies} \quad u f = O_P(ut)$$

$$f = o_P(t) \quad u \in T \quad \text{implies} \quad u f = o_P(ut)$$

Proposition (R)

If $\text{REDUCTION}(p, P) = 0$ or $p \xrightarrow{P}^* 0$ then $p = O_P(\text{LT}(p))$.

Proof.

Easy exercise. □

Characterizations of Gröbner Bases

When $f = O_G(\text{LT}(f))$ we say that f has a standard representation wrt G .

Theorem

G is a Gröbner basis if and only if $\forall 0 \neq f \in \text{Id}(G), f = O_G(\text{LT}(f))$.

Proof.

...



and what happen when

$$f \neq O_G(\text{LT}(f)) ?$$

Sum of polynomials

$$f \in I = \text{Id}(f_1, \dots, f_m)$$

By definition:

$$f = g_1 f_1 + \dots + g_m f_m$$

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Not a unique representation !

$$\begin{array}{r} g_1 f_1 \quad \bullet \quad \bullet \quad \dots \\ + g_2 f_2 \quad \bullet \quad \bullet \quad \dots \\ + g_3 f_3 \quad \bullet \quad \dots \\ + g_4 f_4 \quad \bullet \quad \dots \\ + g_5 f_5 \quad \bullet \quad \dots \\ \vdots \end{array}$$

Sum of polynomials

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By definition:

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$$\begin{array}{r} g_1 f_1 \quad \bullet \quad \bullet \quad \dots \\ + g_2 f_2 \quad \bullet \quad \bullet \quad \dots \\ + g_3 f_3 \quad \quad \bullet \quad \dots \\ + g_4 f_4 \quad \quad \bullet \quad \dots \\ + g_5 f_5 \quad \quad \bullet \quad \dots \\ \vdots \\ \hline = \quad 0 \quad 0 \quad \bullet \quad \dots \end{array}$$

Sum of polynomials

$$f \in I = \text{Id}(f_1, \dots, f_m)$$

By definition:

$$f = g_1 f_1 + \dots + g_m f_m$$

Not a unique representation !

$S(f_1, f_2) ?$

$$\begin{array}{r} g_1 f_1 \bullet \dots \\ + g_2 f_2 \bullet \dots \\ + g_3 f_3 \bullet \dots \\ + g_4 f_4 \bullet \dots \\ + g_5 f_5 \bullet \dots \\ \vdots \end{array}$$

$$= 0 0 \bullet \dots$$

Characterizations of Gröbner Bases

Theorem

G is a Gröbner basis if and only if $\forall 0 \neq f \in \text{Id}(G), f = O_G(\text{LT}(f))$.

Theorem

Let G be a finite subset of polynomials. If for all g_1, g_2 in G , we have $\text{Spol}(g_1, g_2) = 0$ or $\text{Spol}(g_1, g_2) = o_G(\text{lcm}(g_1, g_2))$, then G is a Gröbner basis.

Proof.

We need to prove a lemma first . . .



Proof of the theorem: lemma

Lemma

Let f_1, \dots, f_k be nonzero polynomials in $\mathbb{K}[x_1, \dots, x_n]$ and $t \in T$. Consider $f = O_P(t) = \sum_{i=1}^k c_i \mathbf{x}^{\alpha_i} f_i$, where $c_i \in \mathbb{K}^*$ such that

$$t = \mathbf{x}^{\alpha_1} LT(f_1) = \dots = \mathbf{x}^{\alpha_k} LT(f_k).$$

If $LT(f) < t$, then $k > 1$ and f can be rewritten:

$$f = \sum_{i=1}^{k-1} b_i \frac{t}{\tau_i} \text{Spol}(f_i, f_{i+1}) \text{ with } b_i \in \mathbb{K}, \quad (9)$$

where $\tau_i = \text{lcm}(f_i, f_{i+1})$. Furthermore

$$\frac{t}{\tau_i} LT(\text{Spol}(f_i, f_{i+1})) < t, \text{ for all } i = 1, \dots, k-1.$$

Characterizations of Gröbner Bases

Corollary (Buchberger)

Let G be a finite subset of polynomials. G is a Gröbner basis if and only if $\text{Spol}(f, g) \xrightarrow{*} 0$ for all $(f, g) \in G^2$.

Corollary (Buchberger)

Let G be a finite subset of polynomials. G is a Gröbner basis if and only if $\text{REDUCTION}(\text{Spol}(f, g), G) = 0$ for all $(f, g) \in G^2$.

Proof.

Let $(f, g) \in G^2$, $f \neq g$. Put $t = \text{LT}(\text{Spol}(f, g)) < \text{lcm}(f, g)$
If $\text{REDUCTION}(\text{Spol}(f, g), G) = 0$ then from proposition (R) :
 $\text{Spol}(f, g) = O_G(\text{LT}(\text{Spol}(f, g))) = O_G(t) = o_G(\text{lcm}(f, g))$ and we can
apply the theorem. □

Buchberger Algorithm

Very simple version of the **Buchberger** algorithm:

Algorithm (Buchberger)

Input: $\left\{ \begin{array}{l} F = [f_1, \dots, f_s] \text{ a list of polynomials} \\ < \text{admissible ordering} \end{array} \right.$

Output: G a finite subset of $\mathbb{K}[x_1, \dots, x_n]$.

$G := F$ and $m := s$

$P := \{(f_i, f_j) \mid 1 \leq i < j \leq m\}$ the list of critical pairs

while $P \neq \emptyset$ **do**

 Select and remove from P a critical pair (f, g)

$f_{m+1} := \text{Spol}(f, g)$

$f_{m+1} := \text{REDUCTION}(f_{m+1}, G)$

if $f_{m+1} \neq 0$ **then**

$m := m + 1$

$P := P \cup \{(f_i, f_m) \mid 1 \leq i < m\}$

$G := G \cup \{f_m\}$

return G

F_4

F_4

The F_4 algorithm

Definition

A critical pairs of (f_i, f_j) is a member of $T^2 \times \mathbb{K}[x_1, \dots, x_n] \times T \times \mathbb{K}[x_1, \dots, x_n]$,

$$\text{Pair}(f_i, f_j) := (\text{lcm}_{ij}, t_i, f_i, t_j, f_j)$$

such that

$$\text{lcm}(\text{Pair}(f_i, f_j)) = \text{lcm}_{ij} = \text{LT}(t_i f_i) = \text{LT}(t_j f_j) = \text{lcm}(f_i, f_j)$$

Definition

We define the degree of the critical pair $\rho_{i,j} = \text{Pair}(f_i, f_j)$, $\deg(\rho_{i,j})$, to be $\deg(\text{lcm}_{i,j})$. We define the following operators:

$$\text{Left}(\rho_{i,j}) := t_i \cdot f_i \quad \text{et} \quad \text{Right}(\rho_{i,j}) := t_j \cdot f_j$$

Algorithm F_4 [5] (simplified version)

Input: $\left\{ \begin{array}{l} F \text{ is a finite subset of } \mathbb{K}[x_1, \dots, x_n] \\ Sel \text{ is a function } List(Pairs) \rightarrow List(Pairs) \\ \text{such that } Sel(I) \neq \emptyset \text{ if } I \neq \emptyset \end{array} \right.$

Output: un sous ensemble fini de $\mathbb{K}[x_1, \dots, x_n]$.

$G := F$, $\tilde{F}_0^+ := F$, $d := 0$ and $P := \{Pair(f, g) \mid (f, g) \in G^2 \text{ with } f \neq g\}$

while $P \neq \emptyset$ **do**

$d := d + 1$

$P_d := Sel(P)$

$P := P \setminus P_d$

$L_d := Left(P_d) \cup Right(P_d)$

$\tilde{F}_d^+ := REDUCTION(L_d, G)$

for $h \in \tilde{F}_d^+$ **do**

$P := P \cup \{Pair(h, g) \mid g \in G\}$

$G := G \cup \{h\}$

return G

We can now extend the definition of reduction of a polynomial modulo a subset of $\mathbb{K}[x_1, \dots, x_n]$, to the reduction of a subset of $\mathbb{K}[x_1, \dots, x_n]$ modulo another subset of $\mathbb{K}[x_1, \dots, x_n]$:

Algorithm REDUCTION

Input: L, G finite subsets of $\mathbb{K}[x_1, \dots, x_n]$

Output: a finite subset of $\mathbb{K}[x_1, \dots, x_n]$ (could be empty).

$F := \text{SYMBOLICPREPROCESSING}(L, G)$

$\tilde{F} :=$ Gaussian reduction of F wrt $<$

$\tilde{F}^+ := \{f \in \tilde{F} \mid \text{LT}(f) \notin \text{LT}(F)\}$ // the “useful” part of \tilde{F}

return \tilde{F}^+

No arithmetic operation is used: it is a symbolic preprocessing.

Algorithm SYMBOLICPREPROCESSING

Input: L, G finite subsets of $\mathbb{K}[x_1, \dots, x_n]$

Output: a finite subset of $\mathbb{K}[x_1, \dots, x_n]$

$F := L$

$Done := LT(F)$

while $T(F) \neq Done$ **do**

 choose m an element of $T(F) \setminus Done$

$Done := Done \cup \{m\}$

if m top réductible modulo G **then**

 exists $g \in G$ and $m' \in T$ such that $m = m' \cdot LT(g)$

$F := F \cup \{m' \cdot g\}$

return F

The SYMBOLICPREPROCESSING function is very efficient: its complexity is proportional to the size of the output (if $\#G$ is smaller than the final size of $T(F)$) [parallel implementation].

Lemma (1)

For all polynomials $p \in L_d$, we have $p \xrightarrow{G \cup \tilde{F}^+} 0$

Theorem

The F_4 algorithm computes a Gröbner basis of G in $\mathbb{K}[x_1, \dots, x_n]$ such that $F \subseteq G$ and $\text{Id}(G) = \text{Id}(F)$.

Proof.

...



Remark

If $\#Sel(I) = 1$ for all $I \neq \emptyset$ then the F_4 algorithm reduces to the Buchberger algorithm. In this case the function Sel is the equivalent of the selection strategy for the Buchberger algorithm.

Selection function

Algorithm Selection

Input: P a list of critical pairs

Output: a list of critical pairs.

$d := \min \{ \deg(\text{lcm}(p)) \mid p \in P \}$

$P_d := \{ p \in P \mid \deg(\text{lcm}(p)) = d \}$

return P_d

We call this strategy *the normal strategy for F_4* .

Hence, if the input polynomials are homogeneous, we obtain in degree d , a d Gröbner basis; *Sel* selects, in the next step, all the critical pairs which are needed to compute the Gröbner basis in degree $d + 1$.

Optimisations

- including Buchberger Criteria (or F_5 criterion).
- reuse **all** the rows in the reduced matrices.

Algorithm Buchberger Criteria - Implementation

$(G_{new}, P_{new}) := \text{UPDATE}(G_{old}, P_{old}, h)$

Input: $\begin{cases} \text{a finite subset } G_{old} \text{ of } \mathbb{K}[x_1, \dots, x_n] \\ \text{a finite subset } P_{old} \text{ of critical pairs in } \mathbb{K}[x_1, \dots, x_n] \\ 0 \neq h \in \mathbb{K}[x_1, \dots, x_n] \end{cases}$

Output: a finite subset in $\mathbb{K}[x_1, \dots, x_n]$ an updated list of critical pairs.

Algorithm F_4 algorithm (with Criteria)

Input: $\left\{ \begin{array}{l} F \subset \mathbb{K}[x_1, \dots, x_n] \\ \text{Sel a function } \text{List}(Pairs) \rightarrow \text{List}(Pairs) \end{array} \right.$

Output: a finite subset of $\mathbb{K}[x_1, \dots, x_n]$.

$G := \emptyset$ and $P := \emptyset$ and $d := 0$

while $F \neq \emptyset$ **do**

$f := \text{first}(F)$; $F := F \setminus \{f\}$

$(G, P) := \text{UPDATE}(G, P, f)$

while $P \neq \emptyset$ **do**

$d := d + 1$

$P_d := \text{Sel}(P)$; $P := P \setminus P_d$

$L_d := \text{Left}(P_d) \cup \text{Right}(P_d)$

$(\tilde{F}_d^+, F_d) := \text{REDUCTION}(L_d, G, (F_i)_{d=1, \dots, (d-1)})$

for $h \in \tilde{F}_d^+$ **do**

$P := P \cup \{\text{Pair}(h, g) \mid g \in G\}$

$(G, P) := \text{UPDATE}(G, P, h)$

return G

F4: step by step

Example (3 quadratic equation in \mathbb{F}_{101})

Monomial ordering is DRL and the normal strategy

$$F = \begin{cases} f_1 = x_1^2 + 66x_1x_2 + 4x_1x_3 + 25x_2^2 + 41x_2x_3 + 54x_3^2 + 42x_1 \\ \quad + 87x_2 + 22x_3 + 86, \\ f_2 = x_1^2 + 22x_1x_2 + 38x_1x_3 + 9x_2^2 + 53x_2x_3 + 6x_3^2 + 92x_1 \\ \quad + 61x_2 + 74x_3 + 49, \\ f_3 = x_1^2 + 13x_1x_2 + 86x_1x_3 + 29x_2^2 + 11x_2x_3 + 81x_3^2 + 98x_1 \\ \quad + 67x_2 + 7x_3 + 40 \end{cases}$$

At the beginning $G = \{f_1\}$ and $P_1 = \{\text{Pair}(f_2, f_3), \text{Pair}(f_1, f_2)\}$ such that $L_1 = \{(1, f_3), (1, f_2), (1, f_1)\}$.

SYMBOLICPREPROCESSING(L_1, G, \emptyset):

$$F_1 = \{f_3, f_2, f_1\} \quad T(F_1) = \{x_1^2, x_1x_2, x_1x_3, x_2^2, x_2x_3, x_3^2, x_1, x_2, x_3, 1\}$$

x_1^2 is already done. All the other monomials are not reducible.

F4: step by step

Example (3 quadratic equation in \mathbb{F}_{101})

At the beginning $G = \{f_1\}$ and $P_2 = \{\text{Pair}(f_2, f_3), \text{Pair}(f_1, f_2)\}$ such that $L_2 = \{(1, f_3), (1, f_2), (1, f_1)\}$.

SYMBOLICPREPROCESSING(L_2, G, \emptyset):

$$F_2 = \{f_3, f_2, f_1\} \quad T(F_2) = \{x_1^2, x_1x_2, x_1x_3, x_2^2, x_2x_3, x_3^2, x_1, x_2, x_3, 1\}$$

x_1^2 is already done. All the other monomials are not reducible.

Matrix representation of $F_1 = [f_3, f_2, f_1]$ is:

$$A_1 = M(F_1) = \begin{array}{c|ccccccc} & x_1^2 & x_1x_2 & x_2^2 & x_1x_3 & x_2x_3 & x_3^2 & \dots \\ f_3 & 1 & 13 & 29 & 86 & 11 & 81 & \dots \\ f_2 & 1 & 22 & 26 & 38 & 53 & 6 & \dots \\ f_1 & 1 & 66 & 25 & 4 & 41 & 54 & \dots \end{array}$$

F4: step by step

Example (3 quadratic equation in \mathbb{F}_{101})

At the beginning $G = \{f_1\}$ and $P_2 = \{\text{Pair}(f_2, f_3), \text{Pair}(f_1, f_2)\}$ such that $L_2 = \{(1, f_3), (1, f_2), (1, f_1)\}$.

SYMBOLICPREPROCESSING(L_2, G, \emptyset):

$$F_2 = \{f_3, f_2, f_1\} \quad T(F_2) = \{x_1^2, x_1x_2, x_1x_3, x_2^2, x_2x_3, x_3^2, x_1, x_2, x_3, 1\}$$

x_1^2 is already done. All the other monomials are not reducible.

$$\widetilde{A}_2 = \begin{array}{c|cccccc} & x_1^2 & x_1x_2 & x_2^2 & x_1x_3 & x_2x_3 & x_3^2 & \dots \\ f_6 & 0 & 0 & 1 & 28 & 19 & 79 & \dots \\ f_5 & 0 & 1 & 0 & 12 & 2 & 5 & \dots \\ f_1 & 1 & 66 & 4 & 25 & 41 & 54 & \dots \end{array}$$

F4: step by step

Example (3 quadratic equation in \mathbb{F}_{101})

At the beginning $G = \{f_1\}$ and $P_2 = \{\text{Pair}(f_2, f_3), \text{Pair}(f_1, f_2)\}$ such that $L_2 = \{(1, f_3), (1, f_2), (1, f_1)\}$.

SYMBOLICPREPROCESSING(L_2, G, \emptyset):

$$F_2 = \{f_3, f_2, f_1\} \quad T(F_2) = \{x_1^2, x_1x_2, x_1x_3, x_2^2, x_2x_3, x_3^2, x_1, x_2, x_3, 1\}$$

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Polynomial representation of \widetilde{A}_2 :

F4: step by step

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Polynomial representation of \widetilde{A}_2 :

$$\begin{aligned} f_5 &= x_1 x_2 + 12 x_1 x_3 + 2 x_2 x_3 + 55 x_3^2 + 66 x_1 + 88 x_2 + 60 x_3 + 92, \\ f_6 &= x_2^2 + 28 x_1 x_3 + 19 x_2 x_3 + 79 x_3^2 + 30 x_1 + 50 x_2 + 59 x_3 + 46 \end{aligned}$$

F4: step by step

Example (3 quadratic equation in \mathbb{F}_{101})

In degree 3: $P_3 = \{\text{Pair}(f_1, f_5), \text{Pair}(f_5, f_6)\}$ such that
 $L_3 = \{(x_2, f_1), (x_1, f_5), (x_2, f_5), (x_1, f_6)\}$.

SYMBOLICPREPROCESSING(L_3, G, \emptyset):

$$F_3 = \{x_2 f_1, x_1 f_5, x_2 f_5, x_1 f_6\}$$

$$T(F_3) = \{\boxed{x_1^2 x_2}, \boxed{x_1 x_2^2}, x_2^3, x_1 x_2 x_3, x_1 x_3^2, x_1 x_3, \dots\}$$

F4: step by step

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$$x_2^3 \text{ is divisible by } x_2 f_6 \longrightarrow F_3 = F_3 \cup \{x_2 f_6\}$$

$$x_1 x_2 x_3 \text{ is divisible by } x_3 f_5 \longrightarrow F_3 = F_3 \cup \{x_3 f_5\}$$

...

F4: step by step

Example (3 quadratic equation in \mathbb{F}_{101})

In degree 3: $P_3 = \{\text{Pair}(f_1, f_5), \text{Pair}(f_5, f_6)\}$ such that
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$$x_2^3 \text{ is divisible by } x_2 f_6 \longrightarrow F_3 = F_3 \cup \{x_2 f_6\}$$

$$x_1 x_2 x_3 \text{ is divisible by } x_3 f_5 \longrightarrow F_3 = F_3 \cup \{x_3 f_5\}$$

...

$$F_3 = [x_2 f_1, x_1 f_5, x_2 f_5, x_1 f_6, x_2 f_6, x_3 f_5, x_3 f_6, f_5, f_6, x_3 f_1, f_1]$$

F4: step by step

Example (3 quadratic equation in \mathbb{F}_{101})

x_2^3 is divisible by $x_2 f_6 \longrightarrow F_3 = F_3 \cup \{x_2 f_6\}$

$x_1 x_2 x_3$ is divisible by $x_3 f_5 \longrightarrow F_3 = F_3 \cup \{x_3 f_5\}$

...

$F_3 = [x_2 f_1, x_1 f_5, x_2 f_5, x_1 f_6, x_2 f_6, x_3 f_5, x_3 f_6, f_5, f_6, x_3 f_1, f_1]$

f_6											1	28	19	79	30	50
f_5										1	0	12	2	55	66	88
.									1	66	25	4	41	54	42	87
.					1	28	19	79	0	0	0	30	50	59	0	0
.				1	0	12	2	55	0	0	0	66	88	60	0	0
$A_3 = .$			1	66	25	4	41	54	0	0	0	42	87	22	0	0
.		1	0	28	19	0	79	0	0	30	50	0	59	0	0	46
$x_2 f_5$	1	0	0	12	2	0	55	0	0	66	88	0	60	0	0	92
f_{10}	1	0	28	19	0	79	0	0	30	50	0	59	0	0	46	0
$x_2 f_1$	1	66	25	0	4	41	0	54	0	0	42	87	0	22	0	86
f_8	1	0	0	12	2	0	55	0	0	66	88	0	60	0	92	0

$$f_{10} = x_1 x_3^2 + 23 x_3^3 + 77 x_1 x_3 + 66 x_2 x_3 + 84 x_3^2 + 48 x_1 + 38 x_2 + 44 x_3 + 68$$

$$f_8 = x_2 x_3^2 + 98 x_3^3 + 60 x_1 x_3 + 34 x_2 x_3 + 85 x_3^2 + 65 x_1 + 9 x_2 + 74 x_3 + 28$$

F4: step by step

Example (Cyclic 4)

Monomial ordering is **DRL** and the **normal strategy**

$$F = \left[\begin{array}{l} f_1 = abcd - 1, f_2 = abc + abd + acd + bcd, \\ f_3 = ab + bc + ad + cd, f_4 = a + b + c + d \end{array} \right]$$

At the beginning $G = \{f_4\}$ and $P_1 = \{\text{Pair}(f_3, f_4)\}$ such that $L_1 = \{(1, f_3), (b, f_4)\}$.

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SYMBOLICPREPROCESSING(L_1, G, \emptyset):

$$F_1 = \{f_3, b f_4\} \quad T(F_1) = \{\boxed{ab}, ad, b^2, bc, bd, cd\}$$

\boxed{ab} is already done.

Example (Cyclic 4)

Monomial ordering is DRL and the normal strategy

$$F = \left[\begin{array}{l} f_1 = abcd - 1, f_2 = abc + abd + acd + bcd, \\ f_3 = ab + bc + ad + cd, f_4 = a + b + c + d \end{array} \right]$$

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$$F_1 = \{f_3, b f_4\} \quad T(F_1) = \{\boxed{ab}, \boxed{ad}, b^2, bc, bd, cd\}$$

ad is top reducible by $f_4 \in G$!

Example (Cyclic 4)

Monomial ordering is DRL and the normal strategy

$$F = \left[\begin{array}{l} f_1 = abcd - 1, f_2 = abc + abd + acd + bcd, \\ f_3 = ab + bc + ad + cd, f_4 = a + b + c + d \end{array} \right]$$

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$$F_1 = \{f_3, b f_4, d f_4\} \quad T(F_1) = \{\boxed{ab}, \boxed{ad}, b^2, bc, bd, cd, d^2\}$$

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Monomial ordering is DRL and the normal strategy

$$F = \left[\begin{array}{l} f_1 = abcd - 1, f_2 = abc + abd + acd + bcd, \\ f_3 = ab + bc + ad + cd, f_4 = a + b + c + d \end{array} \right]$$

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SYMBOLICPREPROCESSING(L_1, G, \emptyset):

$F_1 = \{f_3, b f_4, d f_4\}$ $T(F_1) = \{\boxed{ab}, \boxed{ad}, \boxed{b^2}, bc, bd, cd, d^2\}$
 b^2 is not reducible by G

Example (Cyclic 4)

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$$F = \left[\begin{array}{l} f_1 = abcd - 1, f_2 = abc + abd + acd + bcd, \\ f_3 = ab + bc + ad + cd, f_4 = a + b + c + d \end{array} \right]$$

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SYMBOLICPREPROCESSING (L_1, G, \emptyset) returns

$$F_1 = [f_3, bf_4, df_4].$$

Example (Cyclic 4)

Matrix representation of $F_1 = [f_3, bf_4, df_4]$ is:

$$A_1 = M(F_1) = \begin{array}{c} df_4 \\ f_3 \\ bf_4 \end{array} \left| \begin{array}{ccccccc} ab & b^2 & bc & ad & bd & cd & d^2 \\ & & & 1 & 1 & 1 & 1 \\ 1 & & 1 & 1 & & 1 & \\ 1 & 1 & 1 & & 1 & & \end{array} \right|$$

Example (Cyclic 4)

Gaussian reduction of A_1 is:

$$\widetilde{A}_1 = \begin{array}{l} df_4 \\ f_3 \\ bf_4 \end{array} \left| \begin{array}{ccccccc} ab & b^2 & bc & ad & bd & cd & d^2 \\ 1 & & 1 & 1 & 1 & 1 & 1 \\ & 1 & & & -1 & & -1 \\ & & 1 & & 2 & & 1 \end{array} \right|$$

Example (Cyclic 4)

$$\widetilde{A}_1 = \begin{array}{l} df_4 \\ f_3 \\ bf_4 \end{array} \left| \begin{array}{ccccccc} ab & b^2 & bc & ad & bd & cd & d^2 \\ & & & 1 & 1 & 1 & 1 \\ 1 & & 1 & & -1 & & -1 \\ & 1 & & & 2 & & 1 \end{array} \right|$$

$$\widetilde{F}_1 = \left[\begin{array}{l} f_5 = ad + bd + cd + d^2, \\ f_6 = ab + bc - bd - d^2, \\ f_7 = b^2 + 2bd + d^2 \end{array} \right]$$

Example (Cyclic 4)

$$\tilde{F}_1 = [f_5 = ad + bd + cd + d^2,$$

$$f_6 = ab + bc - bd - d^2,$$

$$f_7 = b^2 + 2bd + d^2]$$

and since $ab, ad \in \text{LT}(F_1)$ we have

$$\tilde{F}_{1+} = [f_7]$$

and now $G = \{f_4, f_7\}$.

Example (Cyclic 4)

For the next step we have to consider $P_2 = \{\text{Pair}(f_2, f_4)\}$
hence $L_2 = \{(1, f_2), (bc, f_4)\}$ and $\mathcal{F} = \{F_1\}$.

Example (Cyclic 4)

$L_2 = \{(1, f_2), (bc, f_4)\}$ et $\mathcal{F} = \{F_1\}$.

In SYMBOLICPREPROCESSING we can try to simplify the products $1 \cdot f_2$ and $bc \cdot f_4$ using the previous computations:

For instance $LT(bc f_4) = abc = LT(c f_6)$ and so instead of $bc \cdot f_4$ we can consider $c \cdot f_6$.

Example (Cyclic 4)

For the next step we have to consider $P_2 = \{\text{Pair}(f_2, f_4)\}$
hence $L_2 = \{(1, f_2), (bc, f_4)\}$ and $\mathcal{F} = \{F_1\}$.

SYMBOLICPREPROCESSING

$$F_2 = \{f_2, c f_6\} \quad T(F_2) = \{\boxed{abc}, bc^2, abd, acd, bcd, cd^2\}$$

Example (Cyclic 4)

For the next step we have to consider $P_2 = \{\text{Pair}(f_2, f_4)\}$
hence $L_2 = \{(1, f_2), (bc, f_4)\}$ and $\mathcal{F} = \{F_1\}$.

SYMBOLICPREPROCESSING

$$F_2 = \{f_2, cf_6\} \quad T(F_2) = \{\boxed{abc}, bc^2, \boxed{abd}, acd, bcd, cd^2\}$$

Example (Cyclic 4)

$$\tilde{F}_1 = [f_5 = ad + bd + cd + d^2, f_6 = ab + bc - bd - d^2, f_7 = b^2 + 2bd + d^2]$$

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hence $L_2 = \{(1, f_2), (bc, f_4)\}$ and $\mathcal{F} = \{F_1\}$.

SYMBOLICPREPROCESSING

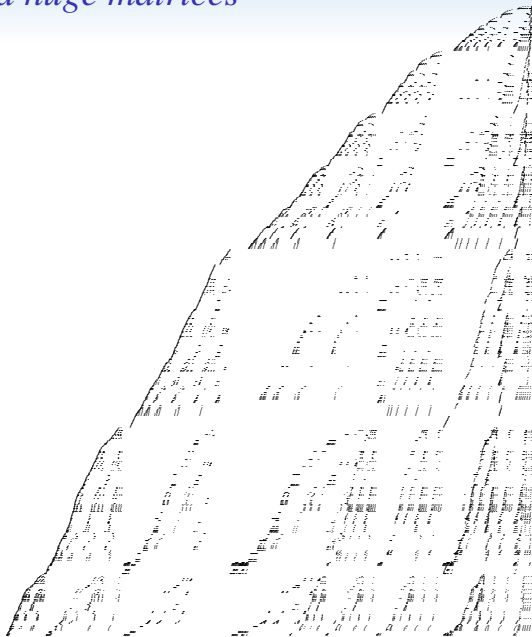
$$F_2 = \{f_2, cf_6\} \quad T(F_2) = \{\boxed{abc}, bc^2, \boxed{abd}, acd, bcd, cd^2\}$$

abd is reducible by $bd f_4$ but also by $b f_5$!

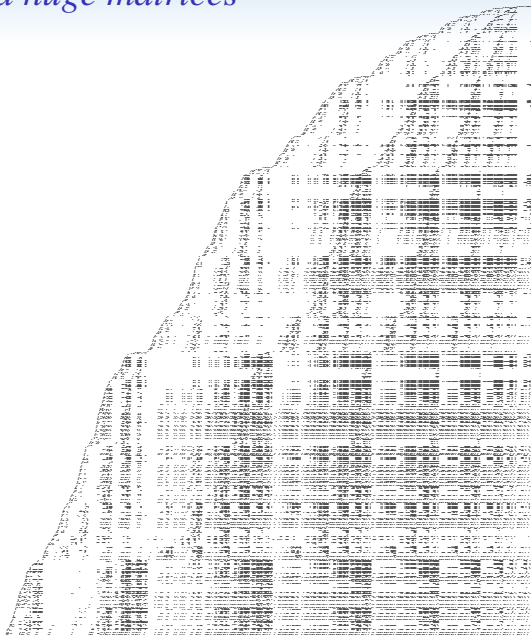
Optimisations

- including Buchberger Criteria (or F_5 criterion).
- reuse **all** the rows in the reduced matrices.
- Improve the **linear algebra** step (dedicated algorithms, matrix compression, ...)

F_4 generated huge matrices



F_4 generated huge matrices



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