

COMPUTING RATIONAL POINTS IN CONVEX SEMI-ALGEBRAIC SETS AND SOS DECOMPOSITIONS

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Abstract. Let $\mathcal{P} = \{h_1, \dots, h_s\} \subset \mathbb{Z}[Y_1, \dots, Y_k]$, $D \geq \deg(h_i)$ for $1 \leq i \leq s$, σ bounding the bit length of the coefficients of the h_i 's, and Φ be a quantifier-free \mathcal{P} -formula defining a convex semi-algebraic set. We design an algorithm returning a rational point in \mathcal{S} if and only if $\mathcal{S} \cap \mathbb{Q} \neq \emptyset$. It requires $\sigma^{O(1)}D^{O(k^3)}$ bit operations. If a rational point is outputted its coordinates have bit length dominated by $\sigma D^{O(k^3)}$. Using this result, we obtain a procedure deciding if a polynomial $f \in \mathbb{Z}[X_1, \dots, X_n]$ is a sum of squares of polynomials in $\mathbb{Q}[X_1, \dots, X_n]$. Denote by d the degree of f , τ the maximum bit length of the coefficients in f , $D = \binom{n+d}{n}$ and $k \leq D(D+1) - \binom{n+2d}{n}$. This procedure requires $\tau^{O(1)}D^{O(k^3)}$ bit operations and the coefficients of the outputted polynomials have bit length dominated by $\tau D^{O(k^3)}$.

Key words. rational sum of squares, semidefinite programming, convex, complexity.

1. Introduction.

Motivation and problem statement. Suppose $f \in \mathbb{R}[x_1, \dots, x_n]$, then f is a sum of squares (SOS) in $\mathbb{R}[x_1, \dots, x_n]$ if and only if it can be written in the form

$$f = v^T \cdot M \cdot v, \tag{1.1}$$

in which v is a column vector of monomials and M is a real positive semidefinite matrix [19, Theorem 1] (see also [4]). The matrix M is also called a *Gram matrix* for f . If M has rational entries, then f is a sum of squares in $\mathbb{Q}[x_1, \dots, x_n]$.

PROBLEM 1.1. (*Sturmfels*). *If $f \in \mathbb{Q}[x_1, \dots, x_n]$ is a sum of squares in $\mathbb{R}[x_1, \dots, x_n]$, then is f also a sum of squares in $\mathbb{Q}[x_1, \dots, x_n]$?*

It has been pointed out that if there is an invertible Gram matrix for f , then there is a Gram matrix for f with rational entries [6, Theorem 1.2]. Furthermore, if $f \in \mathbb{Q}[x_1, \dots, x_n]$ is a sum of m squares in $K[x_1, \dots, x_n]$, where K is a totally real number field with Galois closure L , then f is also a sum of $4m \cdot 2^{[L:\mathbb{Q}]+1} \binom{[L:\mathbb{Q}]+1}{2}$ squares in $\mathbb{Q}[x_1, \dots, x_n]$ [6, Theorem 1.4]. It is interesting to see that the number of squares can be reduced to m (see [9]).

Although no example is known of a rational polynomial having only irrational sum of squares, a complete answer to Question 1.1 is not known. This is the main motivation for us to design an algorithm to check whether a rational polynomial having a rational sum of squares decomposition and give the rational SOS representation if it does exist. By reducing this problem to semidefinite programming, this can be done by designing an algorithm checking if a convex semi-algebraic set contains rational points (see [19]).

Main result. We propose an algorithm which decides if a *convex* semi-algebraic set $\mathcal{S} \subset \mathbb{R}^k$ contains rational points, i.e., points with coordinates in \mathbb{Q}^k . In the case where $\mathcal{S} \cap \mathbb{Q}^k$ is non-empty, a rational point in \mathcal{S} is computed.

The semi-algebraic set \mathcal{S} is given as the solution set of a polynomial system of non-strict inequalities with integer coefficients. Arithmetic operations, sign evaluations and comparisons of two integers/rationals can be done in polynomial time of the maximum bit length of the considered integers/rationals.

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We bound the number of bit operations that the algorithm performs with respect to the number of polynomials, their degrees and the maximum bit length of their input coefficients; we also give upper bounds on the bit length of the coordinates of the outputted rational point if this situation occurs. More precisely, the main result is as follows.

THEOREM 1.1. *Consider a set of polynomials $\mathcal{P} = \{h_1, \dots, h_s\} \subset \mathbb{Z}[Y_1, \dots, Y_k]$, and a quantifier-free \mathcal{P} -formula $\Phi(Y_1, \dots, Y_k)$ and let D be an integer such that $\deg(h_i) \leq D$ for $1 \leq i \leq s$ and σ the maximum bit length of the coefficients of the h_i 's. Let $\mathcal{S} \subset \mathbb{R}^k$ be the convex semi-algebraic set defined by Φ . There exists an algorithm which decides if $\mathcal{S} \cap \mathbb{Q}^k$ is non-empty within $\sigma^{O(1)}(sD)^{O(k^3)}$ bit operations. In case of non-emptiness, it returns an element of $\mathcal{S} \cap \mathbb{Q}^k$ whose coordinates have bit length dominated by $\sigma D^{O(k^3)}$.*

We use a procedure due to [1] performing quantifier elimination over the reals in order to deduce from Theorem 1.1 the following result.

COROLLARY 1.2. *Let $\mathcal{S} \subset \mathbb{R}^k$ be a convex set defined by*

$$\mathcal{S} = \{Y \in \mathbb{R}^k : (Q_1 X^{[1]} \in \mathbb{R}^{n_1}) \dots (Q_\omega X^{[\omega]} \in \mathbb{R}^{n_\omega}) P(Y, X^{[1]}, \dots, X^{[\omega]})\}$$

with quantifiers $Q_i \in \{\exists, \forall\}$, where $X^{[i]}$ is a set of n_i variables, P is a Boolean function of s atomic predicates

$$g_i(Y, X^{[1]}, \dots, X^{[\omega]}) \Delta_i 0$$

where $\Delta_i \in \{>, <, =\}$ (for $i = 1, \dots, s$) and the g_i 's are polynomials of degree D with integer coefficients of binary size at most σ . There exists an algorithm which decides if $\mathcal{S} \cap \mathbb{Q}^k$ is non-empty within $\sigma^{O(1)}(sD)^{O(k^3 \prod_{i=1}^\omega n_i)}$ bit operations. In case of non-emptiness, it returns an element of $\mathcal{S} \cap \mathbb{Q}^k$ whose coordinates have bit length dominated by $\sigma D^{O(k^3 \prod_{i=1}^\omega n_i)}$.

The proof of the above results is based on quantitative and algorithmic results for computing sampling points in semi-algebraic sets and quantifier elimination over the reals.

It is well-known that deciding if a given polynomial $f \in \mathbb{Z}[X_1, \dots, X_n]$ of degree d whose coefficients have bit length dominated by τ is a sum of squares of polynomials in $\mathbb{Q}[X_1, \dots, X_n]$ can be reduced to a linear matrix inequality which defines a convex semi-algebraic set (see e.g. [19]). Applying Theorem 1.1, we show that there exists an algorithm deciding if such an SOS decomposition exists over the rationals and that the coefficients of the polynomials in the decomposition have bit length dominated by $\tau D^{O(k^3)}$ with $D = \binom{n+d}{n}$ and $k \leq D(D+1) - \binom{n+2d}{n}$. Moreover, such a decomposition can be found within $\tau^{O(1)} D^{O(k^3)}$ bit operations.

Prior works. Khachiyan and Porkolab extended the well-known result of [14] on the polynomial-time solvability of linear integer programming in fixed dimension to semidefinite integer programming. The following proposition is given in [10, 11].

PROPOSITION 1.3. *Let $\mathcal{S} \subset \mathbb{R}^k$ be a convex set defined as in Corollary 1.2. There exists an algorithm for solving the problem $\min\{Y_k | Y = (Y_1, \dots, Y_k) \in \mathcal{S} \cap \mathbb{Z}^k\}$ in time $\ell^{O(1)}(sD)^{O(k^4 \prod_{i=1}^\omega O(n_i))}$. In case of non-emptiness, then the minimization problem has an optimal solution whose bit length is dominated by $\ell D^{O(k^4 \prod_{i=1}^\omega O(n_i))}$.*

Their algorithm was further improved by Heinz for the case of convex minimization where the feasible region is described by quasiconvex polynomials [5].

Although we can apply Proposition 1.3 directly to certify that a given polynomial with integer coefficients to be non-negative for all real values of the variables by

computing a sum of squares in $\mathbb{Z}[x_1, \dots, x_n]$, the nonnegativity of a polynomial can be certified if it can be written as a sum of squares of polynomials in $\mathbb{Q}[x_1, \dots, x_n]$. Some hybrid symbolic-numeric algorithms have been given in [16, 17, 7, 8] which turn a numerical sum of squares representation of a positive polynomial into an exact rational identity. However, it is well known that there are plenty of polynomials which are nonnegative but can not be written as sums of squares of polynomials, for example, the famous Motzkin polynomial. This also impel us to study Khachiyan and Porkolab's approach. It turns out that by focusing on rational numbers instead of integers, we can design an exact and cheaper algorithm which decide whether a given polynomial can be written as an SOS over the rationals and give the rational SOS decomposition if it exists.

Structure of the paper. Section 2 is devoted to recall the quantitative and algorithmic results on computing sampling points in semi-algebraic sets and quantifier elimination over the reals. Most of these results are proved in [1]. Section 3 is devoted to prove the correctness of the algorithm on which Theorem 1.1 and Corollary 1.2 rely. The complexity analysis is done in Section 4 and leads to the estimates stated in Theorem 1.1. In Section 5, we apply Theorem 1.1 to prove the announced bounds on the bit length of the rational coefficients of the decomposition into sums of squares of a given polynomial with integer coefficients.

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2. Preliminaries. The algorithm on which Theorem 1.1 relies and its complexity analysis are based on algorithmic and quantitative results on computing sampling points in semi-algebraic sets and quantifier elimination over the reals.

2.1. Computing points in semi-algebraic sets. Consider a set of polynomials $\mathcal{P} = \{h_1, \dots, h_J\} \subset \mathbb{Z}[Y_1, \dots, Y_k]$, and a quantifier-free \mathcal{P} -formula $\Phi(Y_1, \dots, Y_k)$, i.e., a quantifier-free formula whose atoms are one of $h = 0$, $h \neq 0$, $h > 0$, $h < 0$ for $h \in \mathcal{P}$. Let D be an integer such that $\deg(h_i) \leq D$ for $1 \leq i \leq J$ and ℓ the maximum bit length of the coefficients of the h_i 's. We denote by $\mathcal{S} \subset \mathbb{R}^k$ the semi-algebraic set defined by $\Phi(Y_1, \dots, Y_k)$.

A function `RealizableSignConditions` computing a set of algebraic points having a non-empty intersection with each connected component of semi-algebraic sets defined by sign conditions satisfied by \mathcal{P} is given in [1, Section 3] (see also [2, Chapter 5]). From this, a function `SamplingPoints` computing a set of algebraic points having a non-empty intersection with each connected component of \mathcal{S} is obtained. These algebraic points are encoded by

- a rational parametrization

$$G = 0, Y_1 = \frac{G_1}{G_0}, \dots, Y_k = \frac{G_k}{G_0}$$

where G, G_0, \dots, G_k are polynomials in $\mathbb{Z}[T]$ such that $\deg(\gcd(G, G_0)) = 0$ and

$$\text{for } 1 \leq i \leq k, -1 \leq \deg(G_i) \leq \deg(G) - 1 \text{ and } 0 \leq \deg(G_0) \leq \deg(G) - 1;$$

the rational parametrization is given by the list $\mathcal{G} = (G, G_0, G_1, \dots, G_k)$; the degree of \mathcal{G} is called *degree of the rational parametrization* and $Z(\mathcal{G}) \subset \mathbb{C}^k$ denotes the set of complex points encoded by \mathcal{G} ;

- and a list \mathcal{T} of the Thom-encodings of the real roots ϑ of G such that $\Phi\left(\frac{G_1(\vartheta)}{G_0(\vartheta)}, \dots, \frac{G_k(\vartheta)}{G_0(\vartheta)}\right)$ is true.

The bit complexity of `SamplingPoints` is $\ell J^{k+1} D^{\mathcal{O}(k)}$ and the output is such that $\deg(G) = \mathcal{O}(D)^k$ and the bit length of the coefficients of G, G_0, G_1, \dots, G_k is dominated by $\ell D^{\mathcal{O}(k)}$.

Factorizing over \mathbb{Q} a univariate polynomial $h \in \mathbb{Q}[T]$ of degree δ with rational coefficients of maximum bit length ℓ can be done in $\ell^{\mathcal{O}(1)} \delta^{\mathcal{O}(1)}$ bit-operations (see [13, 21, 20]). Given a root ϑ of h , the minimal polynomial of ϑ has coefficients of bit length dominated by $\ell + \mathcal{O}(\delta)$ (see [15]).

Consider now a root ϑ of G and its minimal polynomial g . Since G and G_0 are co-prime, one can compute $G_0^{-1} \bmod g$ to obtain a rational parametrization (g, g_0, \dots, g_k) with integer coefficients of bit length dominated by $\ell D^{\mathcal{O}(k)}$ and

$$\text{for } 1 \leq i \leq k, -1 \leq \deg(g_i) \leq \deg(g) - 1 \text{ and } 0 \leq \deg(g_0) \leq \deg(g) - 1$$

within a bit-complexity $\ell^{\mathcal{O}(1)} D^{\mathcal{O}(k)}$. This implies the following result.

PROPOSITION 2.1. *There exists a function `SemiAlgebraicSolve` which takes as input the system $\Phi(Y_1, \dots, Y_k)$ and computes a rational parametrization $\mathcal{G} = (G, G_0, G_1, \dots, G_k)$ and a list \mathcal{T} of Thom-encodings such that G is irreducible over \mathbb{Q} , and \mathcal{T} contains the encodings of the real roots ϑ of G such that $\left(\frac{G_1(\vartheta)}{G_0(\vartheta)}, \dots, \frac{G_k(\vartheta)}{G_0(\vartheta)}\right) \in \mathcal{S}$. The bit length of the coefficients of G, G_0, G_1, \dots, G_k is dominated by $\ell D^{\mathcal{O}(k)}$ and $\deg(G) = \mathcal{O}(D)^k$. Moreover, `SemiAlgebraicSolve` requires $\ell^{\mathcal{O}(1)} J^{k+1} D^{\mathcal{O}(k)}$ bit operations.*

REMARK 2.2. *Since G and G_0 are co-prime, one can compute $G_0^{-1} \bmod G$ in polynomial time, and the binary length of its rational coefficients can be bounded via subresultants, we can assume, without loss of generality, that the rational parametrization has a constant denominator:*

$$Y = \frac{1}{q}(G_1(\vartheta), G_2(\vartheta), \dots, G_k(\vartheta)) \in \mathcal{S}, \quad G(\vartheta) = 0, \quad (2.1)$$

where the bit length of q and the coefficients of G, G_1, \dots, G_k are dominated by $\ell D^{\mathcal{O}(k)}$.

The above discussion leads also to the following result.

PROPOSITION 2.3. *Let \mathcal{G}, \mathcal{T} be the output of `SemiAlgebraicSolve`(Φ), δ be the degree of G , and ℓ be the maximum bit length of the coefficients of the polynomials in $\mathcal{G} \cup \mathcal{P}$. There exists a function `RationalZeroDimSolve` which takes as input \mathcal{G} and Φ and returns a rational point $y \in Z(\mathcal{G})$ if and only if $y \in \mathcal{S} \cap Z(\mathcal{G}) \cap \mathbb{Q}^k$, else it returns an empty list. The coordinates of these rational points have bit length dominated by $\ell \delta^{\mathcal{O}(1)}$ and computations are performed within $\mathcal{O}(k) \mathcal{O}(J) \ell^{\mathcal{O}(1)} \delta^{\mathcal{O}(1)} \binom{n+D}{n}^{\mathcal{O}(1)}$ bit operations.*

REMARK 2.4. *According to Proposition 2.1, the function `SemiAlgebraicSolve` computes a rational parametrization $\mathcal{G} = (G, G_0, G_1, \dots, G_k)$ such that G is irreducible over \mathbb{Q} . Therefore a rational point $y \in Z(\mathcal{G})$ if and only if $\deg(G) = 1$. In order to check whether $y \in \mathcal{S}$, we only need to evaluate the formula Φ at y .*

The following result is a restatement of [1, Theorem 4.1.2] and allows us to bound the bit length of rational points in non-empty semi-algebraic sets defined by strict polynomial inequalities.

PROPOSITION 2.5. *Let $\mathcal{S}' \subset \mathbb{R}^k$ be a semi-algebraic set defined by a quantifier-free \mathcal{P} -formula whose atoms are strict inequalities. Then \mathcal{S}' contains a rational point whose coordinates have bit length dominated by $\ell D^{O(k)}$.*

The proof of the above result (see [1, Proof of Theorem 4.1.2 pp. 1032]) is based on the routine `RealizableSignConditions` and the isolation of real roots of univariate polynomials with rational coefficients (see e.g. [2, Chapter 10]). We denote by `RationalOpenSemiAlgebraicSolve` a function taking as input the \mathcal{P} -formula Φ and which returns a rational point in \mathcal{S} if and only if there exists a non-empty semi-algebraic set \mathcal{S}' defined by a quantifier-free \mathcal{P} -formula whose atoms are strict inequalities such that $\mathcal{S}' \subset \mathcal{S}$. The result below is not stated in [1] but is an immediate consequence of this proof.

COROLLARY 2.6. *Suppose that there exists a quantifier-free \mathcal{P} -formula whose atoms are strict inequalities defining a non-empty semi-algebraic set $\mathcal{S}' \subset \mathcal{S}$. There exists an algorithm computing a rational point in \mathcal{S} if and only if $\mathcal{S} \neq \emptyset$. It requires $\ell^{O(1)} J^{k+1} D^{O(k)}$ bit operations and if a rational point is outputted, its coordinates have bit length dominated by $\ell D^{O(k)}$.*

2.2. Quantifier elimination over the reals. We consider now a first-order formula F over the reals

$$(Q_1 X^{[1]} \in \mathbb{R}^{n_1}) \dots (Q_\omega X^{[\omega]} \in \mathbb{R}^{n_\omega}) P(Y, X^{[1]}, \dots, X^{[\omega]})$$

where

- $Y = (Y_1, \dots, Y_k)$ is the vector of free variables;
- each Q_i ($i = 1, \dots, \omega$) is one of the quantifiers \exists or \forall ;
- $P(Y, X^{[1]}, \dots, X^{[\omega]})$ is a Boolean function of s atomic predicates

$$g(Y, X^{[1]}, \dots, X^{[\omega]}) \Delta_i 0$$

where $\Delta_i \in \{>, <, =\}$ (for $i = 1, \dots, s$) and the g_i 's are polynomials of degree D with integer coefficients of binary size at most ℓ .

The following result on quantifier elimination is a restatement of [1, Theorem 1.3.1].

THEOREM 2.7. *There exists a quantifier-free formula Ψ*

$$\bigvee_{i=1}^I \bigwedge_{j=1}^{J_i} (h_{ij} \Delta_{ij} 0)$$

(where $h_{ij} \in \mathbb{Z}[Y_1, \dots, Y_k]$ and $\Delta_{ij} \in \{=, >\}$) which is equivalent to F and such that

- $I \leq s^{(k+1)\Pi_{i=1}^\omega(n_i+1)} D^{(k+1)\Pi_{i=1}^\omega(n_i)}$,
- $J_i \leq s^{\Pi_{i=1}^\omega(n_i+1)} D^{\Pi_{i=1}^\omega(n_i)}$,
- $\deg(h_{ij}) \leq D^{\Pi_{i=1}^\omega(n_i)}$,
- the bit length of the coefficients of the h_{ij} 's is dominated by $\ell D^{(k+1)\Pi_{i=1}^\omega(n_i)}$.

The above transformation requires $\ell s^{(k+1)\Pi_{i=1}^\omega(n_i+1)} D^{(k+1)\Pi_{i=1}^\omega(n_i)}$ bit operations.

In the sequel, we denote by `QuantifierElimination` a function that takes F as input and returns a list $[\Psi_1, \dots, \Psi_I]$ where the Ψ_i 's are the conjunctions

$$\bigwedge_{j=1}^{J_i} (h_{ij} \Delta_{ij} 0).$$

3. Algorithm and correctness.

3.1. Description of the algorithm. We use the following functions:

- **Substitute** which takes as input a variable $Y_r \in \{Y_1, \dots, Y_k\}$, a polynomial $h \in \mathbb{Q}[Y_1, \dots, Y_k]$ and a Boolean formula F and which returns a formula \tilde{F} obtained by substituting Y_r by h in F .
- **RemoveDenominators** which takes as input a formula F and returns a formula \tilde{F} obtained by multiplying the polynomials in F by the absolute value of the least common multiple of the denominators of their coefficients.
- **Open** which takes as input a system Φ of equations and inequalities in $\mathbb{Q}[Y_1, \dots, Y_k]$ and returns the inconsistent system $1 = 0$ if Φ contains equations $h = 0$ (where h is not identically 0) else it returns the system obtained by substituting all non-strict inequalities by strict inequalities.

Consider a rational parametrization $\mathcal{G} = (G, G_0, G_1, \dots, G_k, G_{k+1}) \subset \mathbb{Z}[T]^{k+3}$ with $\delta = \deg(G)$. For $0 \leq i \leq \delta - 1$, denote by $\mathbf{a}_i \in \mathbb{Z}^k$ the vector of integers whose j -th coordinate is the coefficient of T^i in G_j . Similarly, for $0 \leq i \leq \delta - 1$, \mathbf{b}_i denotes the coefficient of T^i in G_{k+1} . We use in the sequel a function **GenerateVectors** that takes as input a rational parametrization \mathcal{G} . This function returns the set list of couples $(\mathbf{a}_i, \mathbf{b}_i)$ for $0 \leq i \leq \delta - 1$.

As in the previous section, consider now a set of polynomials $\mathcal{P} = \{h_1, \dots, h_s\} \subset \mathbb{Z}[Y_1, \dots, Y_k]$, and a quantifier-free \mathcal{P} -formula $\Phi(Y_1, \dots, Y_k)$ and let D be an integer such that $\deg(h_i) \leq D$ for $1 \leq i \leq s$ and σ the maximum bit length of the coefficients of the h_i 's. We denote by $\mathcal{S} \subset \mathbb{R}^k$ the semi-algebraic set defined by $\Phi(Y_1, \dots, Y_k)$ which is supposed to be convex.

The routine **FindRationalPoints** below takes as input the formula $\Phi(Y_1, \dots, Y_k)$ defining $\mathcal{S} \subset \mathbb{R}^k$ and a list of variables $[Y_1, \dots, Y_k]$.

FindRationalPoints($\Phi, [Y_1, \dots, Y_k]$).

1. Let $L = \text{RationalOpenSemiAlgebraicSolve}(\text{Open}(\Phi))$
2. If L is not empty then return L
3. Let $\mathcal{G}, \mathcal{T} = \text{SemiAlgebraicSolve}(\Phi)$
4. If \mathcal{T} is empty then return $[\]$
5. Let $L = \text{RationalZeroDimSolve}(\mathcal{G}, \Phi)$
6. If L is not empty or $k = 1$ then return L
7. Else
 - (a) Let A_1, \dots, A_k, B be free variables and Θ be the formula

$$\forall Y \in \mathbb{R}^k \quad A_1^2 + \dots + A_k^2 > 0 \wedge (\neg \Phi \vee A_1 Y_1 + \dots + A_k Y_k = B)$$

- (b) Let $[\Psi_1, \dots, \Psi_I] = \text{QuantifierElimination}(\Theta)$ and $i = 1$
- (c) While $i \leq I$ do
 - i. $\mathcal{G}, \mathcal{T} = \text{SemiAlgebraicSolve}(\Psi_i)$ and $(G, G_0, G_1, \dots, G_k, G_{k+1}) = \mathcal{G}$
 - ii. If \mathcal{T} is empty $i = i + 1$ else break
- (d) Let $C = \text{GenerateVectors}(G, G_0, G_1, \dots, G_k, G_{k+1})$
- (e) Let $a = (a_1, \dots, a_k) \neq (0, \dots, 0)$ and $b \in \mathbb{Z}$ such that $(a, b) \in C$
- (f) Let $r = \max(i, 1 \leq i \leq k \text{ and } a_i \neq 0)$
- (g) Let $h = b - \frac{\sum_{j=1}^{r-1} a_j Y_j}{a_r}$
- (h) Let $\Phi' = \text{RemoveDenominators}(\text{Substitute}(Y_r, h, \Phi))$
- (i) Let $L = \text{FindRationalPoints}(\Phi', [Y_1, \dots, Y_{r-1}, Y_{r+1}, \dots, Y_k])$
- (j) If L is not empty
 - i. Let $(q_1, \dots, q_{r-1}, q_{r+1}, \dots, q_k)$ be its element

- ii. Let $q_r = \text{Evaluate}(\{Y_i = q_i, 1 \leq i \leq k, j \neq r\}, h)$
- iii. If $\Phi(q_1, \dots, q_{r-1}, q_r, q_{r+1}, \dots, q_k)$ is true then return $[(q_1, \dots, q_{r-1}, q_r, q_{r+1}, \dots, q_k)]$ else return $[\]$
- (k) Else return $[\]$

PROPOSITION 3.1. *The algorithm FindRationalPoints returns a list containing a rational point if and only if $\mathcal{S} \cap \mathbb{Q}^k$ is non-empty, else it returns an empty list.*

The next paragraph is devoted to prove this proposition.

REMARK 3.2. *Let $\mathcal{S} \subset \mathbb{R}^k$ be a convex set defined by*

$$\mathcal{S} = \{Y \in \mathbb{R}^k : \mathbb{R}^k(Q_1 X^{[1]} \in \mathbb{R}^{n_1}) \dots (Q_\omega X^{[\omega]} \in \mathbb{R}^{n_\omega}) P(Y, X^{[1]}, \dots, X^{[\omega]})\}$$

with quantifiers $Q_i \in \{\exists, \forall\}$, where $X^{[i]}$ is a set of n_i variables, P is a Boolean function of s atomic predicates

$$g(Y, X^{[1]}, \dots, X^{[\omega]}) \Delta_i 0$$

where $\Delta_i \in \{>, <, =\}$ (for $i = 1, \dots, s$).

Denote by Θ the quantified formula defining \mathcal{S} and by $[\Psi_1, \dots, \Psi_I]$ the output of QuantifierElimination(Θ). Running FindRationalPoints on the Ψ_i 's allows to decide the existence of rational points in \mathcal{S} . This proves a part of Corollary 1.2.

3.2. Proof of correctness. A semi-algebraic set A can be partitioned in cells which are homeomorphic to \mathbb{R}^i for some $i \in \mathbb{N}$. The maximum of those i is the *dimension* of the semi-algebraic set under consideration. Following [3, Definition 2.8.1 and Proposition 2.8.2 pp.50], the *dimension* of A coincides with the Krull dimension of the ideal associated to the smallest algebraic variety containing A . As a by-product, the dimension of A coincides with the dimension of the smallest real algebraic set containing A , that we denote by $\text{Var}(A)$ in the sequel. By convention, the dimension of the empty set is -1 .

We reuse the notations introduced in the description of FindRationalPoints and $\mathcal{S} \subset \mathbb{R}^k$ denotes the semi-algebraic set defined by the formula Φ given as input. The proof is done by induction on k . We will first investigate the case $k = 1$: in this case, $\dim(\mathcal{S})$ is either 1, -1 or 0. In all these cases, we will prove that Steps (1-6) return a rational point in \mathcal{S} if and only if $\mathcal{S} \cap \mathbb{Q}^k \neq \emptyset$. In the case where $k > 1$, we will use the fact that \mathcal{S} is convex to prove that it is contained in an affine subspace. An equation defining a hyperplane containing this affine subspace is obtained in Step (7b). This equation may have algebraic coefficients but we will be able to use it in order to reduce the search of a rational point in $\mathcal{S} \subset \mathbb{R}^k$ to the search of a rational point in a semi-algebraic set lying in \mathbb{R}^{k-1} .

Preliminaries. We start with some lemmas.

LEMMA 3.3. *Let $A \subset \mathbb{R}^k$ be a semi-algebraic set defined by a quantifier-free \mathcal{P} -formula. If $\dim(A) = k$ there exists $y \in A$ such that for all $h \in \mathcal{P} \setminus \{0\}$ $h(y) \neq 0$.*

Proof. Suppose that for all $y \in A$, there exists $h \in \mathcal{P}$ such that $h(y) = 0$. Then, A is contained in the union \mathcal{H} of the hypersurfaces defined by $h = 0$ for $h \in \mathcal{P}$. Consequently, $\dim(A) \leq \dim(\mathcal{H}) < k$, which contradicts $\dim(A) = k$. \square

LEMMA 3.4. *Suppose that $0 \leq \dim(\mathcal{S}) < k$. There exists $(a_1, \dots, a_k) \in \mathbb{R}^k$ and $b \in \mathbb{R}$ such that $(a_1, \dots, a_k) \neq (0, \dots, 0)$ and*

$$\forall (y_1, \dots, y_k) \in \mathbb{R}^k \quad (y_1, \dots, y_k) \in \mathcal{S} \implies a_1 y_1 + \dots + a_k y_k = b. \quad (3.1)$$

Proof. It is sufficient to prove that $\text{Var}(\mathcal{S})$ is an affine subspace of \mathbb{R}^k of dimension less than k : in this case, there exists a real affine hyperplane $H \subsetneq \mathbb{R}^k$ (defined by $\sum_{i=1}^k a_i Y_i = b$ for $(a_1, \dots, a_k) \in \mathbb{R}^k \setminus (0, \dots, 0)$ and $b \in \mathbb{R}$) such that $\mathcal{S} \subset \text{Var}(\mathcal{S}) \subset H$.

Since \mathcal{S} is convex, if $\dim(\mathcal{S}) = 0$ then \mathcal{S} is a single point; thus the conclusion follows immediately.

We suppose now that $\dim(\mathcal{S}) > 0$; hence \mathcal{S} is not empty and contains infinitely many points. Consider $y_0 \in \mathcal{S}$. Given $y \in \mathbb{R}^k \setminus \{y_0\}$, we denote by $L_{y_0, y} \subset \mathbb{R}^k$ the real line containing y and y_0 and by $H_{y_0, y} \subset \mathbb{R}^k$ the real affine hyperplane which is orthogonal to $L_{y_0, y}$ and which contains y_0 .

Since \mathcal{S} is convex, for all $y \in \mathcal{S} \setminus \{y_0\}$, $\mathcal{S} \cap L_{y, y_0} \neq \emptyset$. We consider the set $\mathcal{U}_{y_0} = \bigcap_{y \in \mathcal{S} \setminus \{y_0\}} H_{y_0, y}$; note that \mathcal{U}_{y_0} is an affine subspace since it is the intersection of affine subspaces. Suppose that the orthogonal of \mathcal{U}_{y_0} is $\text{Var}(\mathcal{S})$. Then, since $\dim(\mathcal{S}) < k$, the orthogonal of \mathcal{U}_{y_0} is an affine subspace of \mathbb{R}^k of dimension less than k containing \mathcal{S} which implies the claimed result.

Thus, it remains to prove that the orthogonal of \mathcal{U}_{y_0} is $\text{Var}(\mathcal{S})$. We first prove that \mathcal{S} is contained in the orthogonal of \mathcal{U}_{y_0} which implies that $\text{Var}(\mathcal{S})$ is contained in the orthogonal of \mathcal{U}_{y_0} . By definition of \mathcal{U}_{y_0} , for all $u \in \mathcal{U}_{y_0}$ and all $y \in \mathcal{S} \setminus \{y_0\}$, the inner product of $\overrightarrow{y_0 u}$ and $\overrightarrow{y_0 y}$ is zero. We prove now that the orthogonal of \mathcal{U}_{y_0} is contained in $\text{Var}(\mathcal{S})$. By definition, the orthogonal of \mathcal{U}_{y_0} is the set of lines L_{y, y_0} for $y \in \mathcal{S} \setminus \{y_0\}$. Thus, it is sufficient to prove that for all $y \in \mathcal{S} \setminus \{y_0\}$, L_{y, y_0} is contained in $\text{Var}(\mathcal{S})$. For all $y \in \mathcal{S} \setminus \{y_0\}$, $\mathcal{S} \cap L_{y, y_0} \neq \emptyset$ because \mathcal{S} is convex. Moreover, $\text{Var}(\mathcal{S} \cap L_{y, y_0})$ is L_{y, y_0} . Since $\mathcal{S} \cap L_{y, y_0} \subset \mathcal{S}$, L_{y, y_0} is contained in $\text{Var}(\mathcal{S})$. Our assertion follows. \square

Correctness when $k = 1$. We prove that in this case Steps (1-6) return a rational point in \mathcal{S} if and only if $\mathcal{S} \cap \mathbb{Q}^k \neq \emptyset$ else an empty list is returned.

If $k = 1$, the dimension of \mathcal{S} is either 1, -1 or 0.

1. Suppose that \mathcal{S} has dimension 1. From Lemma 3.3, there exists a non-empty semi-algebraic set $\mathcal{S}' \subset \mathcal{S}$ defined by a quantifier-free \mathcal{P} -formula whose atoms are strict inequalities. Thus \mathcal{S}' contains a rational point. From Corollary 2.6, such a rational point in \mathcal{S} is outputted at Step (1).
2. Suppose that \mathcal{S} has dimension -1 , i.e., \mathcal{S} is empty. From Proposition 2.1, the list of Thom-encodings outputted at Step (3) is empty and the empty list is returned at Step (4).
3. Suppose that \mathcal{S} has dimension 0. Since \mathcal{S} is convex, this implies that \mathcal{S} is a single point contained in $Z(\mathcal{G})$. From Proposition 2.3, this point is outputted at Step (5) if and only if it is a rational point; else the empty list is outputted.

The case $k > 1$. Our induction assumption is that, given a quantifier-free \mathcal{P}' -formula Φ' (with $\mathcal{P}' \subset \mathbb{Z}[Y_1, \dots, Y_{k-1}]$) defining a convex semi-algebraic set $\mathcal{S}' \subset \mathbb{R}^{k-1}$, `FindRationalPoints` returns a list containing a rational point if and only if $\mathcal{S}' \cap \mathbb{Q}^{k-1}$ is non-empty, else it returns an empty list.

Suppose first that $\dim(\mathcal{S}) = k$. Then, by Lemma 3.3, $\mathcal{S} \cap \mathbb{Q}^k$ is not empty and a rational point is outputted at Step (2) by Corollary 2.6.

Suppose now that $\dim(\mathcal{S}) < k$. Then, the interior of \mathcal{S} is empty and Corollary 2.6 implies that the list L computed at Step (1) is empty. If \mathcal{S} is empty then, according to Proposition 2.1, an empty list is returned at Step (4). Suppose now that \mathcal{S} is not empty and that no rational point is outputted at Step (6). Hence, we enter at Step (7). Note that the formula Θ (Step (7a)) defines the semi-algebraic set $\mathcal{A} \subset \mathbb{R}^k \times \mathbb{R}$ such that $(a_1, \dots, a_k, b) \in \mathcal{A}$ if and only if $(a_1, \dots, a_k) \neq (0, \dots, 0)$ and

$$\forall (y_1, \dots, y_k) \in \mathbb{R}^k \quad (y_1, \dots, y_k) \in \mathcal{S} \implies a_1 y_1 + \dots + a_k y_k = b.$$

Thus, the quantifier-free formula $\bigvee_{i=1}^I \Psi_i$ (Step (7b)) defines \mathcal{A} . Remark that by Lemma 3.4, \mathcal{A} is not empty. Hence, the loop at Step (7c) ends by finding a rational parametrization $\mathcal{G} = (G, G_0, G_1, \dots, G_k, G_{k+1})$ (computed at Step (7ci)) which encodes some points in \mathcal{A} .

From the specification of `SemiAlgebraicSolve`, G is irreducible over \mathbb{Q} . Let $a = (a_1, \dots, a_k) \in \mathbb{R}^k$ and $b \in \mathbb{R}$ such that $(a, b) \in \mathcal{A} \cap Z(\mathcal{G})$. Then, there exists a real root ϑ of G such that

$$G_0(\vartheta) \begin{pmatrix} a \\ b \end{pmatrix} = \sum_{i=1}^{\deg(G)-1} \vartheta^i \begin{pmatrix} \mathbf{a}_i \\ \mathbf{b}_i \end{pmatrix} \quad (3.2)$$

where the couples $(\mathbf{a}_i, \mathbf{b}_i) \in \mathbb{Z}^k \times \mathbb{Z}$ are those returned by `GenerateVectors` (Step (7d)). Since $\gcd(G_0, G) = 1$, $G_0(\vartheta) \neq 0$. Moreover, $(a, b) \in \mathcal{A}$ implies $a \neq (0, \dots, 0)$. Note also that $(a, b) \in \mathcal{A}$ implies that for all $\lambda \in \mathbb{R}^*$, $(\lambda a, \lambda b) \in \mathcal{A}$ since for all $(y_1, \dots, y_k) \in \mathcal{S}$ and $\lambda \in \mathbb{R}^*$

$$a_1 y_1 + \dots + a_k y_k = b \iff \lambda(a_1 y_1 + \dots + a_k y_k) = \lambda b$$

This proves that

$$(a^*, b^*) = (G_0(\vartheta)a, G_0(\vartheta)b) \in \mathcal{A} \text{ and } (a_1^*, \dots, a_k^*) \neq (0, \dots, 0).$$

Thus, there exists i such that $\mathbf{a}_i \neq 0$, which implies that Step (7e) never fails. To end the proof of correctness, we distinguish the case where $\mathcal{S} \cap \mathbb{Q}^k$ is empty or not.

The non-empty case. We suppose first that $\mathcal{S} \cap \mathbb{Q}^k$ is non-empty; let $(y_1, \dots, y_k) \in \mathcal{S} \cap \mathbb{Q}^k$. Using (3.2), the linear relation $a_1^* y_1 + \dots + a_k^* y_k = b^*$ implies the algebraic relation of degree $\deg(G) - 1$:

$$\sum_{i=0}^{\deg(G)-1} \vartheta^i \left(\sum_{j=1}^k \mathbf{a}_{i,j} y_j - \mathbf{b}_i \right) = 0, \quad (3.3)$$

where $\mathbf{a}_{i,j}$ is the j -th coordinate of \mathbf{a}_i . Since G is irreducible, it is the minimal polynomial of ϑ ; hence ϑ is an algebraic number of degree $\deg(G)$. Thus, (3.3) is equivalent to

$$\forall 0 \leq i \leq \deg(G) - 1, \quad \sum_{j=1}^k \mathbf{a}_{i,j} y_j = \mathbf{b}_i.$$

We previously proved that there exists i such that $\mathbf{a}_i \neq 0$. We let $a = (a_1, \dots, a_k) \in \mathbb{Z}^k \setminus (0, \dots, 0)$ and $b \in \mathbb{Z}$ be respectively the vector with integer coordinates and the integer chosen in C (Step (7e)). We have just proved that $\mathcal{S} \cap \mathbb{Q}^k$ is contained in the intersection of \mathcal{S} and of the affine hyperplane H defined by $a_1 Y_1 + \dots + a_k Y_k = b$. Note also that $\mathcal{S} \cap H$ is convex since \mathcal{S} is convex and H is an affine hyperplane.

Consider the projection $\pi_r : (y_1, \dots, y_k) \in \mathbb{R}^k \rightarrow (y_1, \dots, y_{r-1}, y_{r+1}, \dots, y_k) \in \mathbb{R}^{k-1}$ for the integer r computed at Step (7f). It is clear that the formula Φ' computed at Step (7h) defines the semi-algebraic set $\pi_r(\mathcal{S} \cap H) \subset \mathbb{R}^{k-1}$. Since $\mathcal{S} \cap H$ is convex, $\pi_r(\mathcal{S} \cap H)$ is convex. Thus, the call to `FindRationalPoints` (Step (7i)) with inputs Φ' and $[Y_1, \dots, Y_{r-1}, Y_{r+1}, \dots, Y_k]$ is valid. From the induction assumption, it returns a rational point in $\pi_r(\mathcal{S} \cap H)$ if and only if $\pi_r(\mathcal{S} \cap H)$ has a non-empty intersection with \mathbb{Q}^{k-1} .

Since $\mathcal{S} \cap \mathbb{Q}^k$ (which is supposed to be non-empty) is contained in $\mathcal{S} \cap H$, $\pi_r(\mathcal{S} \cap H)$ contains rational points. Thus, the list L (Step (7i)) contains a rational point $\mathbf{q}_{k-1} = (q_1, \dots, q_{r-1}, q_{r+1}, \dots, q_k) \in \pi_r(\mathcal{S} \cap H)$. This implies that $\pi_r^{-1}(\mathbf{q}_{k-1}) \cap H$ has a non-empty intersection with $\mathcal{S} \cap H$. Remark that $\pi_r^{-1}(\mathbf{q}_{k-1}) \cap H$ is the rational point $\mathbf{q} = (q_1, \dots, q_{r-1}, q_r, q_{r+1}, \dots, q_k)$ where q_r is computed at Step (7jii). It belongs to \mathcal{S} since $\pi_r^{-1}(\mathbf{q}_{k-1}) \cap H$ and $\mathcal{S} \cap H$ have a non-empty intersection. Thus, $\Phi(q_1, \dots, q_{r-1}, q_r, q_{r+1}, \dots, q_k)$ is true and \mathbf{q} is returned by `FindRationalPoints`.

The empty case. Suppose now that $\mathcal{S} \cap \mathbb{Q}^k$ is empty. As above H denotes the affine hyperplane defined by $a_1 Y_1 + \dots + a_k Y_k = b$ where $(a_1, \dots, a_k) \in \mathbb{Z}^k$ and $b \in \mathbb{Z}$ are chosen at Step (7e). Using the above argumentation, $\pi_r(\mathcal{S} \cap H)$ is convex and the formula Φ' (Step (7h)) defines $\pi_r(\mathcal{S} \cap H)$. Thus, the call to `FindRationalPoints` (Step (7i)) with inputs Φ' and $[Y_1, \dots, Y_{r-1}, Y_{r+1}, \dots, Y_k]$ is valid. Suppose that $\pi_r(\mathcal{S} \cap H)$ does not contain rational points. Then, by the induction assumption, L is empty and the empty list is returned (Step (7j)) which is the expected output since we have supposed $\mathcal{S} \cap \mathbb{Q}^k = \emptyset$. Else, L contains a rational point $(q_1, \dots, q_{r-1}, q_{r+1}, \dots, q_k)$. Consider the rational point $(q_1, \dots, q_{r-1}, q_r, q_{r+1}, \dots, q_k)$ (where q_r is computed at Step (7jii)). It can not belong to \mathcal{S} since we have supposed $\mathcal{S} \cap \mathbb{Q}^k$ is empty. Consequently, $\Phi(q_1, \dots, q_{r-1}, q_r, q_{r+1}, \dots, q_k)$ is false and the empty list is returned.

4. Complexity.

We analyze now the bit complexity of `FindRationalPoints`.

LEMMA 4.1. *Steps (1-6) of `FindRationalPoints`(Φ) perform within $\sigma^{O(1)} s^{k+1} D^{O(k)}$ bit operations. If a rational point is returned at Step (6) or Step (2), its coordinates have bit length dominated by $\sigma D^{O(k)}$.*

Proof. The result is a direct consequence of the results stated at Section 2.

1. From Corollary 2.6, Step (1) is performed within $\sigma s^{k+1} D^{O(k)}$ bit operations and if a rational point is outputted at Step (2), its coordinates have bit length dominated by $\sigma D^{O(k)}$.
2. From Proposition 2.1, Steps (3) and (4) are performed within $\sigma^{O(1)} s^{k+1} D^{O(k)}$ bit operations.
3. From Proposition 2.3, Step (5) requires $\sigma^{O(1)} D^{O(k)}$ bit operations. Moreover, if a rational point is outputted at Step (6), its coordinates have bit length dominated by $\sigma D^{O(k)}$.

□

LEMMA 4.2.

1. *Steps (7a-7h) require $\sigma^{O(1)} (sD)^{O(k^2)}$ bit operations. The number of polynomials in Φ' is s ; their degrees are dominated by D and the bit length of their coefficients is dominated by $\sigma D^{O(k^2)}$.*
2. *If a rational point with coordinates of bit length dominated by ℓ is returned at Steps (7i-7j), the rational number computed at Step (7jii) has bit length dominated by $\ell + \sigma D^{O(k^2)}$.*

Proof. From Theorem 2.7, Steps (7a-7b) are performed within $\sigma s^{O(k^2)} D^{O(k^2)}$ bit operations. The obtained quantifier-free formula is a disjunction of $(sD)^{O(k^2)}$ conjunctions. Thus the loop (Step (7c)) makes at most $(sD)^{O(k^2)}$ calls to `SemiAlgebraicSolve`. Each conjunction involves $(sD)^{O(k)}$ polynomials of degree $D^{O(k)}$ in $\mathbb{Z}[A_1, \dots, A_k, B]$ with integers of bit length dominated by $\sigma D^{O(k^2)}$. Thus, from Proposition 2.1, each call to `SemiAlgebraicSolve` is performed within $\sigma^{O(1)} D^{O(k^2)}$ bit operations. Since there are at most $(sD)^{O(k^2)}$ such calls, Step (7ci) is performed within $\sigma^{O(1)} (sD)^{O(k^2)}$ bit operations and outputs a rational parametrization of degree $D^{O(k^2)}$ with integer coefficients of bit length dominated by $\sigma D^{O(k^2)}$.

Thus, the integers in the list computed at Step (7d) have bit length dominated by $\sigma D^{O(k^2)}$ and are obtained within a bit complexity dominated by $\sigma^{O(1)}(sD)^{O(k^2)}$. This implies that the polynomial h obtained from Steps (7e-7g) has rational coefficients of bit length dominated by $\sigma D^{O(k^2)}$ and is obtained within a bit complexity dominated by $\sigma^{O(1)}(sD)^{O(k^2)}$. Assertion (2) follows immediately.

The substitution phase and removal of the denominators (Step (7h)) can be performed in polynomial time in the maximum bit length of the coefficients of h and those of the polynomials in Φ , i.e., $\sigma D^{O(k^2)}$, the maximum degree of the polynomials in Φ , i.e., D and the number of polynomials in Φ , i.e., s . This cost is still dominated by the cost of Step (7c). As announced, the obtained formula Φ' contains $s(k-1)$ -variate polynomials of degree D with integer coefficients of bit length dominated by $\sigma D^{O(k^2)}$. \square

PROPOSITION 4.3. *Consider a set of polynomials $\mathcal{P} = \{h_1, \dots, h_s\} \subset \mathbb{Z}[Y_1, \dots, Y_k]$, and a quantifier-free \mathcal{P} -formula $\Phi(Y_1, \dots, Y_k)$ and let D be an integer such that $\deg(h_i) \leq D$ for $1 \leq i \leq s$ and σ the maximum bit length of the coefficients of the h_i 's. Then, $\text{FindRationalPoints}(\Phi, [Y_1, \dots, Y_k])$ requires $\sigma^{O(1)}(sD)^{O(k^3)}$ bit operations. Moreover, if it outputs a rational point, its coordinates have bit length dominated by $\sigma D^{O(k^3)}$.*

Proof. We prove Proposition 4.3 by induction on k . The initialization of the induction is immediate from the correctness when $k = 1$ and Lemma 4.1.

Suppose that $k > 1$. Suppose that the execution of $\text{FindRationalPoints}(\Phi)$ stops at Steps (2), or (4) or (6). From Lemma 4.1, we are done. Suppose now that we enter in Step (7).

By Lemma 4.2(1), the formula Φ' computed at Step (7h) contains $s(k-1)$ -variate polynomials of degree D and coefficients of bit length dominated by $\sigma D^{O(k^2)}$ and is obtained within $\sigma^{O(1)}(sD)^{O(k^2)}$ bit operations. The induction assumption implies that

- Step (7i) requires $\sigma^{O(1)}(sD)^{O(k^3)}$ bit operations,
- If a rational point is contained in L (Step (7j)), its coordinates have bit length dominated by $\sigma D^{O(k^3)}$.

Hence, by Lemma 4.2(2), the rational number computed at Step (7jii) has bit length dominated by $\sigma D^{O(k^3)}$. Moreover, Steps (7jii-7jiii) have a cost which is the one of evaluating the input formula Φ at rational points. Thus, the cost is log-linear in the maximum bit length of the coordinates of the rational point in L , i.e., $\sigma D^{O(k^3)}$ the maximum degree of the polynomials in Φ , i.e., D and the number of polynomials in Φ , i.e., s . \square

4.1. Proof of Corollary 1.2. We prove now Corollary 1.2 that we restate below: Let $\mathcal{S} \subset \mathbb{R}^k$ be a convex set defined by

$$\mathcal{S} = \{Y \in \mathbb{R}^k : (Q_1 X^{[1]} \in \mathbb{R}^{n_1}) \dots (Q_\omega X^{[\omega]} \in \mathbb{R}^{n_\omega}) P(Y, X^{[1]}, \dots, X^{[\omega]})\}$$

with quantifiers $Q_i \in \{\exists, \forall\}$, where $X^{[i]}$ is a set of n_i variables, P is a Boolean function of s atomic predicates

$$g_i(Y, X^{[1]}, \dots, X^{[\omega]}) \Delta_i 0$$

where $\Delta_i \in \{>, <, =\}$ (for $i = 1, \dots, s$) and the g_i 's are polynomials of degree D with integer coefficients of binary size at most σ . There exists an algorithm which decides if $\mathcal{S} \cap \mathbb{Q}^k$ is non-empty within $\sigma^{O(1)}(sD)^{O(k^3 \prod_{i=1}^\omega n_i)}$ bit operations. In case

of non-emptiness, it returns an element of $\mathcal{S} \cap \mathbb{Q}^k$ whose coordinates have bit length dominated by $\sigma D^{O(k^3 \Pi_{i=1}^\omega n_i)}$.

Proof. Denote by Θ the quantified formula defining \mathcal{S} . Theorem 2.7 states that $\text{QuantifierElimination}(\Theta)$ requires $\sigma s^{(k+1)\Pi_{i=1}^\omega(n_i+1)} D^{(k+1)\Pi_{i=1}^\omega O(n_i)}$ bit operations. It outputs a list of conjunctions Φ_1, \dots, Φ_I with $I \leq s^{(k+1)\Pi_{i=1}^\omega(n_i+1)} D^{(k+1)\Pi_{i=1}^\omega O(n_i)}$, and for $1 \leq i \leq I$, Φ_i is a conjunction of $J_i \leq s^{\Pi_{i=1}^\omega(n_i+1)} D^{\Pi_{i=1}^\omega O(n_i)}$ atomic predicates $h \Delta 0$ with $h \in \mathbb{Z}[Y_1, \dots, Y_k]$, $\Delta \in \{=, >\}$ and $\deg(h) \leq D^{\Pi_{i=1}^\omega O(n_i)}$ and the bit length of the coefficients of the polynomials h_{ij} is dominated by $\sigma D^{(k+1)\Pi_{i=1}^\omega O(n_i)}$. Thus, the cost of running $\text{FindRationalPoints}$ on all the Φ_i 's requires $\sigma^{O(1)} (sD)^{O(k^3 \Pi_{i=1}^\omega n_i)}$ bit operations. In case of non-emptiness of $\mathcal{S} \cap \mathbb{Q}^k$, it returns an element of $\mathcal{S} \cap \mathbb{Q}^k$ whose coordinates have bit length dominated by $\sigma D^{O(k^3 \Pi_{i=1}^\omega n_i)}$. This ends to prove Corollary 1.2. \square

5. Rational sums of squares. Consider a polynomial $f \in \mathbb{Z}[x_1, \dots, x_n]$ of degree $2d$ whose coefficients have bit length bounded by τ . If we choose v as the vector of all monomials in $\mathbb{Z}[x_1, \dots, x_n]$ of degree less than or equal to d , then we consider the set of real symmetric matrices $M = M^T$ of dimension $D = \binom{n+d}{n}$ for which $f = v^T \cdot M \cdot v$. By Gaussian elimination, it follows that there exists an integer $k \leq \frac{1}{2}D(D+1) - \binom{n+2d}{n}$ such that

$$M = \{M_0 + Y_1 M_1 + \dots + Y_k M_k, Y_1, \dots, Y_k \in \mathbb{R}\} \quad (5.1)$$

for some rational symmetric matrices M_0, \dots, M_k . The polynomial f can be written as a sum of squares of polynomials if and only if the matrix M can be completed as a symmetric positive semidefinite matrix (see [12]). Let $Y = (Y_1, \dots, Y_k)$, we define

$$\mathcal{S} = \{Y \in \mathbb{R}^k \mid M(Y) \succeq 0, M(Y) = M(Y)^T, f = v^T \cdot M(Y) \cdot v\}. \quad (5.2)$$

It is clear that $\mathcal{S} \subseteq \mathbb{R}^k$ is a convex set defined by setting all polynomials in

$$\Phi(Y_1, \dots, Y_k) = \{(-1)^{(i+D)} m_i, i = 0, \dots, D-1\} \quad (5.3)$$

to be nonnegative, where the m_i 's are the coefficients of the characteristic polynomial of $M(Y)$. The cardinality s of Φ is bounded by D and Φ contains polynomials of degree bounded by D whose coefficients have bit length bounded by τD (see [19]). Hence the semi-algebraic set defined by (5.2) is

$$\mathcal{S} = \{(Y_1, \dots, Y_k) \in \mathbb{R}^k \mid (-1)^{(i+D)} m_i \geq 0, 0 \leq i \leq D-1\}. \quad (5.4)$$

The result below is obtained by applying Theorem 1.1 to the semi-algebraic set defined above.

COROLLARY 5.1. *Let $f \in \mathbb{Z}[x_1, \dots, x_n]$ of degree $2d$ with integers of bit length bounded by τ . By running the algorithm $\text{FindRationalPoints}$ for the semi-algebraic set defined in (5.2), one can decide whether f is a sum of squares in $\mathbb{Q}[x_1, \dots, x_n]$ within $\tau^{O(1)} D^{O(k^3)}$ bit operations. Suppose $f = \sum f_i^2, f_i \in \mathbb{Q}[x_1, \dots, x_n]$, then the bit lengths of rational coefficients of the f_i 's are bounded by $\tau D^{O(k^3)}$.*

REMARK 5.2. *Applying Proposition 1.3 by Khachiyan and Porkolab to the semi-algebraic set defined in (5.2), one can decide whether f is a sum of squares in $\mathbb{Z}[x_1, \dots, x_n]$ within $\tau^{O(1)} D^{O(k^4)}$ operations. Suppose that $f = \sum f_i^2$ (with $f_i \in \mathbb{Z}[x_1, \dots, x_n]$), then the bit lengths of integer coefficients of f_i are bounded by $\tau D^{O(k^4)}$.*

Porkolab and Khachiyan showed that the non-emptiness of the convex set defined in (5.2) over the reals can be determined in $O(kD^4) + D^{O(\min\{k, D^2\})}$ arithmetic operations over $\ell D^{O(\min\{k, D^2\})}$ -bit numbers, where ℓ is the maximal bit length of the matrices M_i (see [18]). Suppose $\mathcal{S} \neq \emptyset$, i.e., $f \in \mathbb{Q}[x_1, \dots, x_n]$ is a sum of squares in $K[x_1, \dots, x_n]$ where K is an algebraic extension of \mathbb{Q} . If K is a totally real number field, then f is also a sum of squares in $\mathbb{Q}[x_1, \dots, x_n]$, i.e., $\mathcal{S} \cap \mathbb{Q}^n \neq \emptyset$ (see [6, 9]). The following lemma and proof can be deduced from arguments given in [9].

LEMMA 5.3. *Suppose $\mathcal{G} = (G, G_0, G_1, \dots, G_k)$ is a rational parametrization for the semi-algebraic set \mathcal{S} defined in (5.2) computed by SemiAlgebraicSolve. Suppose ϑ is a real root of G such that*

$$Y(\vartheta) = \frac{1}{q}(G_1(\vartheta), G_2(\vartheta), \dots, G_k(\vartheta)) \in \mathcal{S}, \quad (5.5)$$

then for any real root ϑ_i of G , we have

$$Y(\vartheta_i) = \frac{1}{q}(G_1(\vartheta_i), G_2(\vartheta_i), \dots, G_k(\vartheta_i)) \in \mathcal{S}. \quad (5.6)$$

Moreover, if G has only real roots, then the point defined by $\frac{1}{\deg G} \sum_{i=1}^{\deg G} Y(\vartheta_i)$ is a rational point in \mathcal{S} .

Proof. Since $Y(\vartheta) \in \mathcal{S}$, the matrix $M(Y(\vartheta))$ is positive semidefinite. We can perform the Gaussian elimination over $\mathbb{Q}(\vartheta)$ to obtain the decomposition $M(Y(\vartheta)) = A(\vartheta)^T A(\vartheta)$. It is clear that for any real root ϑ_i of G , $M(Y(\vartheta_i)) = A(\vartheta_i)^T A(\vartheta_i)$ is also positive semidefinite, i.e., $Y(\vartheta_i) \in \mathcal{S}$. Moreover, if G has only real roots ϑ_i , then $\sum_{\vartheta_i, G(\vartheta_i)=0} G_j(\vartheta_i) \in \mathbb{Q}$. It follows that the point defined by $\frac{1}{\deg G} \sum_{i=1}^{\deg G} Y(\vartheta_i)$ is a rational point in \mathcal{S} . \square

The above discussion leads to the following result.

THEOREM 5.4. *Suppose $f \in \mathbb{Z}[x_1, \dots, x_n]$. There exists a function RationalTotalRealSolve which either determines that f can not be written as sum of squares over the reals or returns a sum of squares representation of f over $\mathbb{Q}[x_1, \dots, x_n]$ if and only if the polynomial G outputted from the function SemiAlgebraicSolve has only real solutions, else it returns an empty list. The coordinates of the rational coefficients of polynomials f_i in $f = \sum_i f_i^2$ have bit length dominated by $\tau D^{O(k)}$ and the bit complexity of RationalTotalRealSolve is $\tau^{O(1)} D^{O(k)}$.*

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